

# Recommended pass through the study plan

## Name of the pass: SpaceMaster - Passage through study

Faculty/Institute/Others: Faculty of Electrical Engineering

Department: Department of Control Engineering

Pass through the study plan: Erasmus Mundus Master Course - SpaceMaster II

Branch of study guaranteed by the department: Cybernetics and Robotics

Guarantor of the study branch: prof. Ing. Michael Šebek, DrSc.

Program of study: Cybernetics and Robotics

Type of study: Follow-up master full-time

Note on the pass:

Coding of roles of courses and groups of courses:

P - compulsory courses of the program, PO - compulsory courses of the branch, Z - compulsory courses, S - compulsory elective courses, PV - compulsory elective courses, F - elective specialized courses, V - elective courses, T - physical training courses

Coding of ways of completion of courses (KZ/Z/ZK) and coding of semesters (Z/L):

KZ - graded assesment, Z - assesment, ZK - examination, L - summer semester, Z - winter semester

Number of semester: 1

| Code      | Name of the course / Name of the group of courses<br>(in case of groups of courses the list of codes of their members)<br><i>Tutors, authors and guarantors (gar.)</i> | Completion | Credits | Scope | Semester | Role |
|-----------|--|------------|---------|-------|----------|------|
| BE3M35CSP | CanSat-Projekt   | Z,ZK       | 9       | 2P+2S | Z        | P    |
| BE3M35ISP | Introduction to Space Physics  | Z,ZK       | 8       | 2P+2S | Z        | P    |
| BE3M35SDY | Space Dynamics   | Z,ZK       | 5       | 2P+2S | Z        | P    |
| BE3M35SSD | Spacecraft System Design   | Z,ZK       | 8       | 2P+2S | Z        | P    |

Number of semester: 2

| Code      | Name of the course / Name of the group of courses<br>(in case of groups of courses the list of codes of their members)<br><i>Tutors, authors and guarantors (gar.)</i> | Completion | Credits | Scope | Semester | Role |
|-----------|--|------------|---------|-------|----------|------|
| BE3M35ELS | Electronics in Space   | Z,ZK       | 8       | 2P+2S | L        | P    |
| BE3M35ORO | Optic- and Radar-based Observations  | Z,ZK       | 8       | 2P+2S | L        | P    |
| BE3M35SPP | Space Plasma Physics   | Z,ZK       | 7       | 2P+2S | Z        | P    |
| BE3M35SEI | Spacecraft Environment Interactions  | Z,ZK       | 7       | 2P+2S | L        | P    |

Number of semester: 3

| Code      | Name of the course / Name of the group of courses<br>(in case of groups of courses the list of codes of their members)<br><i>Tutors, authors and guarantors (gar.)</i> | Completion | Credits | Scope | Semester | Role |
|-----------|--|------------|---------|-------|----------|------|
| BE3M35CSA | Control Systems for Aircraft and Spacecraft<br><i>Martin Hromčík Martin Hromčík Martin Hromčík (Gar.)</i>  | Z,ZK       | 7       | 2P+2L | Z        | P    |
| BE3M35IDP | Individuální projekt<br><i>Kristian Hengster-Movric Kristian Hengster-Movric Kristian Hengster-Movric (Gar.)</i>   | Z          | 8       | 0P+6S | Z        | P    |
| BE3M35SSM | Space systems, modeling and identification<br><i>Petr Hušek Petr Hušek Petr Hušek (Gar.)</i>   | Z,ZK       | 7       | 4P+2C | Z        | P    |

Number of semester: 4

| Code      | Name of the course / Name of the group of courses<br>(in case of groups of courses the list of codes of their members)<br><i>Tutors, authors and guarantors (gar.)</i> | Completion | Credits | Scope | Semester | Role |
|-----------|--|------------|---------|-------|----------|------|
| BE3M35DIP | Diploma Thesis<br><i>Kristian Hengster-Movric, Martin Hlinovský Martin Hlinovský Kristian Hengster-Movric (Gar.)</i>   | Z          | 30      | 22S   | L        | P    |

|           |   |      |   |       |   |   |
|-----------|---|------|---|-------|---|---|
| BE3M35ORC | <b>Optimal and robust control design</b><br>Zdeněk Hurák Zdeněk Hurák Zdeněk Hurák (Gar.) | Z,ZK | 8 | 2P+2C | L | P |
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## List of groups of courses of this pass with the complete content of members of individual groups

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### List of courses of this pass:

| Code      | Name of the course  | Completion | Credits |
|-----------|---|------------|---------|
| BE3M35CSA | Control Systems for Aircraft and Spacecraft<br>System Approach. Object, System, Model. Dynamic Systems Continuous and Discrete Time, Qualitative Analysis of Systems. Poincare Map, Chaos. Linear Systems. System Stability, Uncertainty and Robustness. Controllability and Observability. State Feedback, State Injection, Duality. Stochastic Systems, Realization of Stochastic Processes.  | Z,ZK       | 7       |
| BE3M35CSP | CanSat-Projekt  | Z,ZK       | 9       |
| BE3M35DIP | Diploma Thesis<br>Independent final comprehensive work for the Master's degree study programme. A student will choose a topic from a range of topics related to his or her branch of study, which will be specified by branch department or branch departments. The diploma thesis will be defended in front of the board of examiners for the comprehensive final examination.   | Z          | 30      |
| BE3M35ELS | Electronics in Space  | Z,ZK       | 8       |
| BE3M35IDP | Individuální projekt<br>Independent work in the form of a project. A student will choose a topic from a range of topics related to his or her branch of study, which will be specified by branch department or branch departments. The project will be defended within the framework of a subject.  | Z          | 8       |
| BE3M35ISP | Introduction to Space Physics   | Z,ZK       | 8       |
| BE3M35ORC | Optimal and robust control design<br>This advanced course on control design will cover modern methods for optimal and robust control design. Emphasis will be put on practical computational design skills. Unifying idea of the course is that of minimization of a system norm. Depending on which norm is minimized, different properties of the resulting controller are guaranteed. Minimizing H2 norm leads to the celebrated LQ/LQG optimal control trading off the performance and the effort, while minimizing Hinf norm shifts the focus to robustness against uncertainties in the model. Mu-synthesis as an extensions to Hinf optimal control design that take the structure of the uncertainty into consideration represents a very powerful tool for robust control design. Standing a little bit aside yet being useful in space missions are the methods for time-optimal and suboptimal control. As a self-contained add-on to the course, introduction to the topic of semidefinite programming and linear matrix inequalities (LMI) will be made, as these constitute a very elegant theoretical and a powerful computational tool for solving all the previously introduced tasks in optimal and robust control. | Z,ZK       | 8       |
| BE3M35ORO | Optic- and Radar-based Observations   | Z,ZK       | 8       |
| BE3M35SDY | Space Dynamics  | Z,ZK       | 5       |
| BE3M35SEI | Spacecraft Environment Interactions   | Z,ZK       | 7       |
| BE3M35SPP | Space Plasma Physics  | Z,ZK       | 7       |
| BE3M35SSD | Spacecraft System Design  | Z,ZK       | 8       |
| BE3M35SSM | Space systems, modeling and identification  | Z,ZK       | 7       |

For updated information see <http://bilakniha.cvut.cz/en/f3.html>

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