Study plan

Name of study plan: Erasmus Mundus Master Course - SpaceMaster 2018

Faculty/Institute/Others: Faculty of Electrical Engineering

Department:

Branch of study guaranteed by the department: Welcome page

Garantor of the study branch:

Program of study: Cybernetics and Robotics Type of study: Follow-up master full-time

Required credits: 120 Elective courses credits: 0 Sum of credits in the plan: 120

Note on the plan:

Name of the block: Compulsory courses in the program

Minimal number of credits of the block: 105

The role of the block: P

Code of the group: 2018_SPACEMASTER_P

Name of the group: Compulsory subjects of the programme

Requirement credits in the group: In this group you have to gain 105 credits

Requirement courses in the group: In this group you have to complete 11 courses

Credits in the group: 105

Note on the group:

Code	Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.)	Completion	Credits	Scope	Semester	Role
ВЕЗМ35АРН	Atmospheric Physics	Z,ZK	8	2P+2S	L	Р
BE3M35CSA	Control Systems for Aircraft and Spacecraft	Z,ZK	7	2P+2L	Z	Р
BE3M35DIP	Diploma Thesis	Z	30	22S	L	Р
BE3M35IDP	Individuální projekt	Z	8	0P+6S	Z	Р
BE3M35ISME	Introduction to Space Mechanics and Electronics	Z	8	0P+4S	Z	Р
BE3M35ORC	Optimal and robust control design	Z,ZK	8	2P+2C	L	Р
BE3M35SPI	Space Instruments	Z,ZK	8	2P+2S	L	Р
BE3M35SPP	Space Physics	Z,ZK	7	2P+2S	Z	Р
BE3M35SSM	Space systems, modeling and identification	Z,ZK	7	4P+2C	Z	Р
BE3M35SEI	Spacecraft Environment Interactions	Z,ZK	7	2P+2S	L	Р
BE3M35TSS	The Solar System	Z,ZK	7	2P+2S	Z	Р

Characteristics of the courses of this group of Study Plan: Code=2018_SPACEMASTER_P Name=Compulsory subjects of the programme

BE3M35APH	Atmospheric Physics	Z,ZK	8		
BE3M35CSA	Control Systems for Aircraft and Spacecraft	Z,ZK	7		
System Approach. Obje	ct, System, Model. Dynamic Systems Continuous and Discrete Time, Qualitative Analysis of Systems. Poincare Map, Chaos.	Linear Systems.	System Stability,		
Uncertainty and Robust	ness. Controllability and Observability. State Feedback, State Injection, Duality. Stochastic Systems, Realization of Stochasti	c Processes.			
BE3M35DIP	Diploma Thesis	Z	30		
Independent final comp	Independent final comprehensive work for the Master's degree study programme. A student will choose a topic from a range of topics related to his or her branch of study, which will				
be specified by branch	be specified by branch department or branch departments. The diploma thesis will be defended in front of the board of examiners for the comprehensive final examination.				
BE3M35IDP	Individuální projekt	Z	8		
Independent work in the form of a project. A student will choose a topic from a range of topics related to his or her branch of study, which will be specified by branch department or					
branch departments. The project will be defended within the framework of a subject.					
BE3M35ISME	Introduction to Space Mechanics and Electronics	Z	8		

BE3M35ORC	Optimal and robust control design	Z,ZK	8
This advanced course of	n control design will cover modern methods for optimal and robust control design. Emphasis will be put on practical computa	itional design skill	s. Unifying idea
of the course is that of n	ninimization of a system norm. Depending on which norm is minimized, different properties of the resulting controller are guar	anteed. Minimizin	g H2 norm leads

of the course is that of minimization of a system norm. Depending on which norm is minimized, different properties of the resulting controller are guaranteed. Minimizing H2 norm leads to the celebrated LQ/LQG optimal control trading off the performance and the effort, while minimizing Hinf norm shifts the focus to robustness against uncertainties in the model. Mu-synthesis as an extensions to Hinf optimal control design that take the structure of the uncertainty into consideration represents a very powerfull tool for robust control design. Standing a little bit aside yet being useful in space missions are the methods for time-optimal and suboptimal control. As a self-contained add-on to the course, introduction to the topic of semidefinite programming and linear matrix inequalities (LMI) will be made, as these constitute a very elegant theoretial and a powerful computational tool for solving all the previously introduced tasks in optimal and robust control.

BE3M35SPI	Space Instruments	Z,ZK	8
BE3M35SPP	Space Physics	Z,ZK	7
BE3M35SSM	Space systems, modeling and identification	Z,ZK	7
BE3M35SEI	Spacecraft Environment Interactions	Z,ZK	7
BE3M35TSS	The Solar System	Z,ZK	7

Name of the block: Compulsory elective courses

Minimal number of credits of the block: 15

The role of the block: PV

Code of the group: 2018_SPACEMASTER_PV

Name of the group: Compulsory optionally subjects

Requirement credits in the group: In this group you have to gain at least 15 credits (at most 41)

Requirement courses in the group: In this group you have to complete at least 2 courses (at most 6)

Credits in the group: 15 Note on the group:

Code	Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.)	Completion	Credits	Scope	Semester	Role
BE3M35ELS	Electronics in Space	Z,ZK	8	2P+2S	L	PV
BE3M35PAT	Polar Atmosphere	Z,ZK	8	2P+2S	L	PV
BE3M35PSA	Propulsion with Space Applications	Z,ZK	7	2P+2S	L	PV
BE3M35SPC	Space Communication	Z,ZK	8	2P+2S	Z	PV
BE3M35SPS	Spacecraft Subsystems	Z,ZK	7	2P+2S	L	PV
BE3M35SIS	Swedish for International Students 1	Z,ZK	3	2P+2S	Z	PV

Characteristics of the courses of this group of Study Plan: Code=2018_SPACEMASTER_PV Name=Compulsory optionally subjects

BE3M35ELS	Electronics in Space	Z,ZK	8	
BE3M35PAT	Polar Atmosphere	Z,ZK	8	
BE3M35PSA	Propulsion with Space Applications	Z,ZK	7	
BE3M35SPC	Space Communication	Z,ZK	8	
BE3M35SPS	Spacecraft Subsystems	Z,ZK	7	
BE3M35SIS	Swedish for International Students 1	Z,ZK	3	

List of courses of this pass:

Code	Name of the course	Completion	Credits			
BE3M35APH	Atmospheric Physics	Z,ZK	8			
BE3M35CSA	Control Systems for Aircraft and Spacecraft	Z,ZK	7			
System Approach.	Object, System, Model. Dynamic Systems Continuous and Discrete Time, Qualitative Analysis of Systems. Poincare Map, Chaos. Lin	ear Systems. Systems	em Stability,			
Uncertai	nty and Robustness. Controllability and Observability. State Feedback, State Injection, Duality. Stochastic Systems, Realization of St	ochastic Processes	S.			
BE3M35DIP	Diploma Thesis	Z	30			
Independent final	Independent final comprehensive work for the Master's degree study programme. A student will choose a topic from a range of topics related to his or her branch of study, which will					
be specified b	by branch department or branch departments. The diploma thesis will be defended in front of the board of examiners for the compreh	ensive final examir	nation.			
BE3M35ELS	Electronics in Space	Z,ZK	8			
BE3M35IDP	Individuální projekt	Z	8			
Independent work in the form of a project. A student will choose a topic from a range of topics related to his or her branch of study, which will be specified by branch department or						
	branch departments. The project will be defended within the framework of a subject.					
BE3M35ISME	Introduction to Space Mechanics and Electronics	Z	8			

BE3M35ORC	Optimal and robust control design	Z,ZK	8			
This advanced course on control design will cover modern methods for optimal and robust control design. Emphasis will be put on practical computational design skills. Unifying idea						
of the course is that	of the course is that of minimization of a system norm. Depending on which norm is minimized, different properties of the resulting controller are guaranteed. Minimizing H2 norm leads					
	LQ/LQG optimal control trading off the performance and the effort, while minimizing Hinf norm shifts the focus to robustness agains					
1	an extensions to Hinf optimal control design that take the structure of the uncertainty into consideration represents a very powerfull t					
	aside yet being useful in space missions are the methods for time-optimal and suboptimal control. As a self-contained add-on to the c					
of semidefinite prog	ramming and linear matrix inequalities (LMI) will be made, as these constitute a very elegant theoretial and a powerful computational to	ool for solving all th	e previously			
	introduced tasks in optimal and robust control.					
BE3M35PAT	Polar Atmosphere	Z,ZK	8			
BE3M35PSA	Propulsion with Space Applications	Z,ZK	7			
BE3M35SEI	Spacecraft Environment Interactions	Z,ZK	7			
BE3M35SIS	Swedish for International Students 1	Z,ZK	3			
BE3M35SPC	Space Communication	Z,ZK	8			
BE3M35SPI	Space Instruments	Z,ZK	8			
BE3M35SPP	Space Physics	Z,ZK	7			
BE3M35SPS	Spacecraft Subsystems	Z,ZK	7			
BE3M35SSM	Space systems, modeling and identification	Z,ZK	7			
BE3M35TSS	The Solar System	Z,ZK	7			

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