# Study plan

## Name of study plan: Erasmus Mundus Master Course - SpaceMaster 2020-22

Faculty/Institute/Others: Faculty of Electrical Engineering
Department:
Branch of study guaranteed by the department: Welcome page
Garantor of the study branch:
Program of study: Cybernetics and Robotics
Type of study: Follow-up master full-time
Required credits: 120
Elective courses credits: 0
Sum of credits in the plan: 120
Note on the plan:

---

Name of the block: Compulsory courses in the program
Minimal number of credits of the block: 98
The role of the block: P

---

Code of the group: 2020_SPACEMASTER_P
Name of the group: Compulsory subjects of the programme
Requirement credits in the group: In this group you have to gain 98 credits
Requirement courses in the group: In this group you have to complete 10 courses
Credits in the group: 98
Note on the group:

| Code | Name of the course / Name of the group of courses *(in case of groups of courses the list of codes of their members)* *Tutors,* ***authors*** *and guarantors (gar.)* | Completion | Credits | Scope | Semester | Role |
|---|---|---|---|---|---|---|
| BE3M35CSA | **Control Systems for Aircraft and Spacecraft** | Z,ZK | 7 | 2P+2L | Z | P |
| BE3M35DIP | **Diploma Thesis** | Z | 30 | 22S | L | P |
| BE3M35IDP | **Individuální projekt** | Z | 8 | 0P+6S | Z | P |
| BE3M35ORC | **Optimal and robust control design** | Z,ZK | 8 | 2P+2C | L | P |
| BE3M35SPC | **Space Communication** | Z,ZK | 8 | 2P+2S | Z | P |
| BE3M35SPI | **Space Instruments** | Z,ZK | 8 | 2P+2S | L | P |
| BE3M35SPP | **Space Physics** | Z,ZK | 7 | 2P+2S | Z | P |
| BE3M35SSM | **Space systems, modeling and identification** | Z,ZK | 7 | 4P+2C | Z | P |
| BE3M35SSD | **Spacecraft System** | Z,ZK | 8 | 2P+2S | Z | P |
| BE3M35TSS | **The Solar System** | Z,ZK | 7 | 2P+2S | Z | P |

**Characteristics of the courses of this group of Study Plan: Code=2020_SPACEMASTER_P Name=Compulsory subjects of the programme**

| | | | |
|---|---|---|---|
| BE3M35CSA | Control Systems for Aircraft and Spacecraft | Z,ZK | 7 |
| System Approach. Object, System, Model. Dynamic Systems Continuous and Discrete Time, Qualitative Analysis of Systems. Poincare Map, Chaos. Linear Systems. System Stability, Uncertainty and Robustness. Controllability and Observability. State Feedback, State Injection, Duality. Stochastic Systems, Realization of Stochastic Processes. | | | |
| BE3M35DIP | Diploma Thesis | Z | 30 |
| Independent final comprehensive work for the Master's degree study programme. A student will choose a topic from a range of topics related to his or her branch of study, which will be specified by branch department or branch departments. The diploma thesis will be defended in front of the board of examiners for the comprehensive final examination. | | | |
| BE3M35IDP | Individuální projekt | Z | 8 |
| Independent work in the form of a project. A student will choose a topic from a range of topics related to his or her branch of study, which will be specified by branch department or branch departments. The project will be defended within the framework of a subject. | | | |
| BE3M35ORC | Optimal and robust control design | Z,ZK | 8 |
| This advanced course on control design will cover modern methods for optimal and robust control design. Emphasis will be put on practical computational design skills. Unifying idea of the course is that of minimization of a system norm. Depending on which norm is minimized, different properties of the resulting controller are guaranteed. Minimizing H2 norm leads to the celebrated LQ/LQG optimal control trading off the performance and the effort, while minimizing Hinf norm shifts the focus to robustness against uncertainties in the model. Mu-synthesis as an extensions to Hinf optimal control design that take the structure of the uncertainty into consideration represents a very powerfull tool for robust control design. Standing a little bit aside yet being useful in space missions are the methods for time-optimal and suboptimal control. As a self-contained add-on to the course, introduction to the topic of semidefinite programming and linear matrix inequalities (LMI) will be made, as these constitute a very elegant theoretial and a powerful computational tool for solving all the previously introduced tasks in optimal and robust control. | | | |
| BE3M35SPC | Space Communication | Z,ZK | 8 |
| BE3M35SPI | Space Instruments | Z,ZK | 8 |

| | | | |
|---|---|---|---|
| BE3M35SPP | Space Physics | Z,ZK | 7 |
| BE3M35SSM | Space systems, modeling and identification | Z,ZK | 7 |
| BE3M35SSD | Spacecraft System | Z,ZK | 8 |
| BE3M35TSS | The Solar System | Z,ZK | 7 |

Name of the block: Compulsory elective courses
Minimal number of credits of the block: 22
The role of the block: PV

Code of the group: 2020_SPACEMASTER_PV
Name of the group: Compulsory optionally subjects
Requirement credits in the group: In this group you have to gain at least 22 credits (at most 40)
Requirement courses in the group: In this group you have to complete at least 3 courses ( at most 6)
Credits in the group: 22
Note on the group:

| Code | **Name of the course / Name of the group of courses** ***(in case of groups of courses the list of codes of their members)*** *Tutors,* ***authors*** *and guarantors (gar.)* | Completion | Credits | Scope | Semester | Role |
|---|---|---|---|---|---|---|
| BE3M35ELS | **Electronics in Space** | Z,ZK | 8 | 2P+2S | L | PV |
| BE3M35MESA | **Microcomputer Engineering with Space Applications** | Z,ZK | 7 | 2P+2S | Z | PV |
| BE3M35PAT | **Polar Atmosphere** | Z,ZK | 8 | 2P+2S | L | PV |
| BE3M35PSA | **Propulsion with Space Applications** | Z,ZK | 7 | 2P+2S | L | PV |
| BE3M35SEI | **Spacecraft Environment Interactions** | Z,ZK | 7 | 2P+2S | L | PV |
| BE3M35SIS | **Swedish for International Students 1** | Z,ZK | 3 | 2P+2S | Z | PV |

**Characteristics of the courses of this group of Study Plan: Code=2020_SPACEMASTER_PV Name=Compulsory optionally subjects**

| | | | |
|---|---|---|---|
| BE3M35ELS | Electronics in Space | Z,ZK | 8 |
| BE3M35MESA | Microcomputer Engineering with Space Applications | Z,ZK | 7 |
| BE3M35PAT | Polar Atmosphere | Z,ZK | 8 |
| BE3M35PSA | Propulsion with Space Applications | Z,ZK | 7 |
| BE3M35SEI | Spacecraft Environment Interactions | Z,ZK | 7 |
| BE3M35SIS | Swedish for International Students 1 | Z,ZK | 3 |

## List of courses of this pass:

| Code | Name of the course | Completion | Credits |
|---|---|---|---|
| BE3M35CSA | Control Systems for Aircraft and Spacecraft | Z,ZK | 7 |
| System Approach. Object, System, Model. Dynamic Systems Continuous and Discrete Time, Qualitative Analysis of Systems. Poincare Map, Chaos. Linear Systems. System Stability, Uncertainty and Robustness. Controllability and Observability. State Feedback, State Injection, Duality. Stochastic Systems, Realization of Stochastic Processes. | | | |
| BE3M35DIP | Diploma Thesis | Z | 30 |
| Independent final comprehensive work for the Master's degree study programme. A student will choose a topic from a range of topics related to his or her branch of study, which will be specified by branch department or branch departments. The diploma thesis will be defended in front of the board of examiners for the comprehensive final examination. | | | |
| BE3M35ELS | Electronics in Space | Z,ZK | 8 |
| BE3M35IDP | Individuální projekt | Z | 8 |
| Independent work in the form of a project. A student will choose a topic from a range of topics related to his or her branch of study, which will be specified by branch department or branch departments. The project will be defended within the framework of a subject. | | | |
| BE3M35MESA | Microcomputer Engineering with Space Applications | Z,ZK | 7 |
| BE3M35ORC | Optimal and robust control design | Z,ZK | 8 |
| This advanced course on control design will cover modern methods for optimal and robust control design. Emphasis will be put on practical computational design skills. Unifying idea of the course is that of minimization of a system norm. Depending on which norm is minimized, different properties of the resulting controller are guaranteed. Minimizing H2 norm leads to the celebrated LQ/LQG optimal control trading off the performance and the effort, while minimizing Hinf norm shifts the focus to robustness against uncertainties in the model. Mu-synthesis as an extensions to Hinf optimal control design that take the structure of the uncertainty into consideration represents a very powerfull tool for robust control design. Standing a little bit aside yet being useful in space missions are the methods for time-optimal and suboptimal control. As a self-contained add-on to the course, introduction to the topic of semidefinite programming and linear matrix inequalities (LMI) will be made, as these constitute a very elegant theoretial and a powerful computational tool for solving all the previously introduced tasks in optimal and robust control. | | | |
| BE3M35PAT | Polar Atmosphere | Z,ZK | 8 |
| BE3M35PSA | Propulsion with Space Applications | Z,ZK | 7 |
| BE3M35SEI | Spacecraft Environment Interactions | Z,ZK | 7 |

| | | | |
|---|---|---|---|
| BE3M35SIS | Swedish for International Students 1 | Z,ZK | 3 |
| BE3M35SPC | Space Communication | Z,ZK | 8 |
| BE3M35SPI | Space Instruments | Z,ZK | 8 |
| BE3M35SPP | Space Physics | Z,ZK | 7 |
| BE3M35SSD | Spacecraft System | Z,ZK | 8 |
| BE3M35SSM | Space systems, modeling and identification | Z,ZK | 7 |
| BE3M35TSS | The Solar System | Z,ZK | 7 |

For updated information see http://bilakniha.cvut.cz/en/f3.html
Generated: day 2025-11-17, time 13:40.