Recomended pass through the study plan

Name of the pass: SpaceMaster - Passage through study

Faculty/Institute/Others: Faculty of Electrical Engineering

Department:

Pass through the study plan: Erasmus Mundus Master Course - SpaceMaster 2018

Branch of study guranteed by the department: Welcome page

Guarantor of the study branch:

Program of study: Cybernetics and Robotics Type of study: Follow-up master full-time

Note on the pass:

Coding of roles of courses and groups of courses:

P - compulsory courses of the program, PO - compulsory courses of the branch, Z - compulsory courses, S - compulsory elective courses, PV - compulsory elective courses, F - elective specialized courses, V - elective courses, T - physical training courses

Coding of ways of completion of courses (KZ/Z/ZK) and coding of semesters (Z/L):

KZ - graded assesment, Z - assesment, ZK - examination, L - summer semester, Z - winter semester

Number of semester: 1

| Code | Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.) | Completion | Credits | Scope | Semester | Role |
|------------|---|------------|---------|-------|----------|------|
| BE3M35ISME | Introduction to Space Mechanics and Electronics | Z | 8 | 0P+4S | Z | Р |
| BE3M35SPI | Space Instruments | Z,ZK | 8 | 2P+2S | L | Р |
| BE3M35SPP | Space Physics | Z,ZK | 7 | 2P+2S | Z | Р |
| BE3M35TSS | The Solar System | Z,ZK | 7 | 2P+2S | Z | Р |

Number of semester: 2

| Code | Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.) | Completion | Credits | Scope | Semester | Role |
|---------------------|---|--------------------------------------|------------------|-------|----------|------|
| BE3M35APH | Atmospheric Physics | Z,ZK | 8 | 2P+2S | L | Р |
| BE3M35SEI | Spacecraft Environment Interactions | Z,ZK | 7 | 2P+2S | L | Р |
| 2018_SPACEMASTER_PV | Compulsory optionally subjects BE3M35ELS,BE3M35PAT, (see the list of groups below) | Min. cours. 2 Max. cours. 6 | Min/Max 15/41 | | | PV |

Number of semester: 3

| Code | Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.) | Completion | Credits | Scope | Semester | Role |
|-----------|---|------------|---------|-------|----------|------|
| BE3M35CSA | Control Systems for Aircraft and Spacecraft | Z,ZK | 7 | 2P+2L | Z | Р |
| BE3M35IDP | Individuální projekt | Z | 8 | 0P+6S | Z | Р |
| BE3M35SSM | Space systems, modeling and identification | Z,ZK | 7 | 4P+2C | Z | Р |

Number of semester: 4

| Code | Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.) | Completion | Credits | Scope | Semester | Role |
|-----------|---|------------|---------|-------|----------|------|
| BE3M35DIP | Diploma Thesis | Z | 30 | 22S | L | Р |
| BE3M35ORC | Optimal and robust control design | Z,ZK | 8 | 2P+2C | L | Р |

List of groups of courses of this pass with the complete content of members of individual groups

| Kód | | Name of the group of group (for specification | courses and on see here o | codes of members of this r below the list of courses) | Com | pletion | Credit | s Scope | Semester | Role |
|--------------|-------------|---|---------------------------|---|------|-------------|-----------------|----------------|------------------|-------|
| | | | | | Min. | cours. | | | | |
| 2018_SPACEMA | ASTER_PV | Compu | Isory optiona | lly subjects | Max | 2 cours. | Min/Ma 15/41 | ıx | | PV |
| | | | | | | 6 | | | | |
| BE3M35ELS | Electronics | in Space | BE3M35PAT | Polar Atmosphere | • | BE3M35 | PSA | Propulsion wi | th Space Applic | catio |
| BE3M35SPC | Space Cor | nmunication | BE3M35SPS | Spacecraft Subsystems | | BE3M35 | SIS | Swedish for Ir | nternational Stu | ıden |

List of courses of this pass:

| Code | Name of the course | Completion | Credits |
|---|---|---|---|
| BE3M35APH | Atmospheric Physics | Z,ZK | 8 |
| BE3M35CSA | Control Systems for Aircraft and Spacecraft | Z,ZK | 7 |
| | Object, System, Model. Dynamic Systems Continuous and Discrete Time, Qualitative Analysis of Systems. Poincare Map, Chaos. Li ty and Robustness. Controllability and Observability. State Feedback, State Injection, Duality. Stochastic Systems, Realization of St | | • |
| BE3M35DIP | Diploma Thesis | Z | 30 |
| Independent final c | omprehensive work for the Master's degree study programme. A student will choose a topic from a range of topics related to his or | her branch of study | , which will |
| be specified by | y branch department or branch departments. The diploma thesis will be defended in front of the board of examiners for the compret | nensive final examin | nation. |
| BE3M35ELS | Electronics in Space | Z,ZK | 8 |
| BE3M35IDP | Individuální projekt | Z | 8 |
| Independent work | in the form of a project. A student will choose a topic from a range of topics related to his or her branch of study, which will be spec | ified by branch dep | artment or |
| | branch departments. The project will be defended within the framework of a subject. | | |
| BE3M35ISME | Introduction to Space Mechanics and Electronics | Z | 8 |
| BE3M35ORC | Optimal and robust control design | Z.ZK | 8 |
| PEDIVIDUOTIVO | Optimal and robast control acaign | ∠,∠ /\ | |
| This advanced cour of the course is that | se on control design will cover modern methods for optimal and robust control design. Emphasis will be put on practical computation of minimization of a system norm. Depending on which norm is minimized, different properties of the resulting controller are guarant | onal design skills. U reed. Minimizing H2 | nifying idea norm leads |
| This advanced cour of the course is that to the celebrated Mu-synthesis as a Standing a little bit a | se on control design will cover modern methods for optimal and robust control design. Emphasis will be put on practical computation of a system norm. Depending on which norm is minimized, different properties of the resulting controller are guarant LQ/LQG optimal control trading off the performance and the effort, while minimizing Hinf norm shifts the focus to robustness agains an extensions to Hinf optimal control design that take the structure of the uncertainty into consideration represents a very powerfull iside yet being useful in space missions are the methods for time-optimal and suboptimal control. As a self-contained add-on to the camming and linear matrix inequalities (LMI) will be made, as these constitute a very elegant theoretial and a powerful computational to | nonal design skills. U need. Minimizing H2 st uncertainties in the tool for robust controduction | nifying idea norm leads ne model. ol design. |
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