## Study plan

## Name of study plan: KOMBI bak. studium od 15-16 (obor LED)

Faculty/Institute/Others:

Department:

Branch of study guaranteed by the department: Welcome page

Garantor of the study branch:

Program of study: Technology in Transportation and Telecommunications

Type of study: Bachelor combined

Required credits: 60

Elective courses credits: 120 Sum of credits in the plan: 180

Note on the plan:

Name of the block: Compulsory courses Minimal number of credits of the block: 60

The role of the block: Z

Code of the group: 1S K LOG LED 15-16 P

Name of the group: 1. sem. bak. KOMBI obory LOG, LED 15-16 povinné p edm ty

Requirement credits in the group: In this group you have to gain 30 credits

Requirement courses in the group: In this group you have to complete 9 courses

Credits in the group: 30 Note on the group:

Code	Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.)	Completion	Credits	Scope	Semester	Role
614AS	Algorithm and Data Structures	KZ	2	0+2	Z	Z
611CAL1	Calculus 1 Romana Zibnerová Ond ej Navrátil (Gar.)	Z,ZK	7	2P+4C+22E	B Z	Z
611GIE	Geometry Vít Malinovský Šárka Vorá ová (Gar.)	KZ	3	2P+2C+12E	B Z	Z
611LA	Linear Algebra Romana Zibnerová Martina Be vá ová (Gar.)	Z,ZK	3	2P+1C+10E	B Z	Z
618MTY	Materials Science and Engineering Vít Malinovský Jaroslav Valach (Gar.)	Z,ZK	3	2P+1C+10E	B Z	Z
620SYSA	Systems Analysis Petr Bureš, Ji í R ži ka Zuzana B linová (Gar.)	Z,ZK	5	2P+2C+14E	L L	Z
618TED	Technical Documentation Vít Malinovský Jitka ezní ková (Gar.)	KZ	2	1P+1C+8E	B Z	Z
616UDOP	Introduction into Vehicles Zuzana Radová Petr Bouchner (Gar.)	Z	2	2P+0C+8E	B Z	Z
612ZYDK	Introduction to Transportation Engineering Dagmar Ko árková Dagmar Ko árková (Gar.)	Z,ZK	3	6B	Z	Z

## Characteristics of the courses of this group of Study Plan: Code=1S K LOG LED 15-16 P Name=1. sem. bak. KOMBI obory LOG, LED 15-16 povinné p edm ty

614AS	Algorithm and Data Structures	KZ	2
Students will be fami	liarized with selected basic and derived data structures, algorithms, their properties and their design procedure. Students will ana	ı lyze problems, pro	pose theoretical
solutions to the set t	ask and the resulting algorithm write by means of flowcharts, practice in reading algorithms recorded by means of the flowchart	and use the basic	cs of Boolean
algebra with forming	the conditions for the algorithms.		
611CAL1	Calculus 1	Z,ZK	7
Sequence of real nu	mbers and its limit. Basic properties of mappings. Function of one real variable, its limit and derivative. Geometric properties of n	dimensional Eukl	idean space and
Cartesian coordinate	e system. Geometric meaning of the differential of functions several real variables, differential calculus of functions of several real	l variables.	
611GIE	Geometry	KZ	3
Orthographic and ob	lique projections, linear perspective. Topographic surfaces and their orthogonal projection. Differential geometry of curves - para	ameterization, arc	of the curve,
torsion and curvatur	e, Frenet`s trihedron. Kinematics - a curve as a trajectory of the motion, the velocity and acceleration of a particle moving on a c	urved path.	
611LA	Linear Algebra	Z,ZK	3
Vector spaces (linea	r combinations, linear independence, dimension, basis, coordinates). Matrices and operations. Systems of linear equations and	their solvability. D	eterminants and
their applications. So	calar product. Similarity of matrices (eigenvalues and eigenvectors). Quadratic forms and their classification.		

618MTY	Materials Science and Engineering	Z,ZK	3
Basic course of materia	s science and engineering explains mechanical properties of structural materials based on their bonding forces and microstru	cture. However th	ne main attention
is paid to metals as the	most important engineering materials, also other major classes of materials are presented, namely ceramics, polymers and	composites. Atter	ition is also paid
to degradation processe	es in materials, to defectoscopy and to main mechanical tests.		
620SYSA	Systems Analysis	Z,ZK	5
Introduction to system s	ciences, system viewpoint, terminology, typical system analysis tasks, system identification, system interface and interface ta	sks, processes, s	ystem behaviour
and its analysis, strong	functions and processes, genetic code, system identity, system architecture. Tools for system analysis - Petri nets, decision to	ables, algorithms	for structural
tasks. Soft and hard sys	stems, methods for soft system analysis.		
618TED	Technical Documentation	KZ	2
Technical standards, int	ernational standardization, technical drawings, representation of technical objects, technical diagrams and charts, dimension	al and geometric	al accuracy,
arrangement of drawing	sheets.		
616UDOP	Introduction into Vehicles	Z	2
Vehicles and transporta	tion systems. Functionality and setup. Movement and drive principles. Engines and their characteristics. Rail, road, air and w	ater transport. Alto	ernative means
of transport. Lifting equi	pment and conveyors. Legislation.		
612ZYDK	Introduction to Transportation Engineering	Z,ZK	3
Pala of transportation in	land use planning Resis terms in transportation engineering Traffic survey and traffic progness. Introduction to topic of read	a publia masa tra	nonort Nogotivo

Code of the group: 2S K LOG LED 15-16 P

Name of the group: 2. sem. bak. KOMBI obory LOG, LED 15-16 povinné p edm ty

Requirement credits in the group: In this group you have to gain 30 credits

Requirement courses in the group: In this group you have to complete 8 courses

Credits in the group: 30

Airlines and economics. Space technologies.

Note on the group:

Code	Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.)	Completion	Credits	Scope	Semester	Role
611CAL2	Calculus 2 Romana Zibnerová Romana Zibnerová Ond ej Navrátil (Gar.)	Z,ZK	5	2P+3C+20E	B L	Z
611FY1	Physics 1	Z,ZK	4	2+2	L	Z
614PRG	Programming Libor Žídek	KZ	2	0P+2C+8E	B L	Z
618SAT	Structural Analysis Tomáš Doktor Daniel Kytý (Gar.)	Z,ZK	4	2P+2C+14E	L	Z
611STAS	Statistics	Z,ZK	5	2+2	L	Z
617TEDK	Transport Technology and Logistics Michal Drábek Vít Janoš (Gar.)	KZ	4	12B	L	Z
621ZALD	Basics of Air Transport Jakub Hospodka	KZ	2	0P+2C+8E	L L	Z
612ZTS	Railway Lines and Stations Tomáš Javo ík, Ond ej Trešl	Z,ZK	4	2P+2C+10E	L L	Z

## Characteristics of the courses of this group of Study Plan: Code=2S K LOG LED 15-16 P Name=2. sem. bak. KOMBI obory LOG, LED 15-16 povinné p edm tv

611CAL2	Calculus 2	Z,ZK	5
Antiderivative, New	onian integral, Riemannian integral of the function of one variable, improper Riemannian integral, Riemannian integral in Rn. P	arametric descriptio	n of regular
k-dimensional surfa	ces in Rn, Riemannian integral over regular surfaces. Line and surface integrals of the second type, Stokes theorems, ordinary	differential equation	ns of the first
order, linear differe	tial equations with constant coefficients and its systems.		
611FY1	Physics 1	Z,ZK	4
Kinematics, particle	dynamics, dynamics of particle systems and rigid body. Continuum mechanics, thermodynamics, electric field, directed electric	current.	
614PRG	Programming	KZ	2
Algorithm developn	ent, methods of structured programming, high-level programming languages, basics of C programming languages (types, varia	bles, conditions, cy	cles, arrays,
unctions), program	ming techniques, complexity.		
S18SAT	Structural Analysis	Z,ZK	4
	Otractara / trialycic	2,21	-
General system of	prices in plane and space. Calculation of reactions of bodies and structures. Assessment of internal forces on statically determine	1 ' 1	-
•		nate beams and sin	nple girders.
Principle of virtual w	orces in plane and space. Calculation of reactions of bodies and structures. Assessment of internal forces on statically determine	nate beams and sin	nple girders.
Principle of virtual w of planar shapes. F	orce's in plane and space. Calculation of reactions of bodies and structures. Assessment of internal forces on statically determin ork. Kinematic method for calculation of reactions of statically determinate systems. Determination of axial forces in truss construct	nate beams and sin	nple girders.
Principle of virtual worf planar shapes. F	orce's in plane and space. Calculation of reactions of bodies and structures. Assessment of internal forces on statically determinate ork. Kinematic method for calculation of reactions of statically determinate systems. Determination of axial forces in truss construct ber polygons and chains.	nate beams and similar beams. Cross-sections	nple girders. al characteristic
Principle of virtual word planar shapes. F 611STAS Definition of probab	orce's in plane and space. Calculation of reactions of bodies and structures. Assessment of internal forces on statically determinate. Kinematic method for calculation of reactions of statically determinate systems. Determination of axial forces in truss construct ber polygons and chains.  Statistics	nate beams and sin	nple girders. al characteristic  5 tical hypothesi
Principle of virtual word planar shapes. F 611STAS Definition of probab Regression and cor	orce's in plane and space. Calculation of reactions of bodies and structures. Assessment of internal forces on statically determinate. Kinematic method for calculation of reactions of statically determinate systems. Determination of axial forces in truss construct ber polygons and chains.  Statistics  lity, random variable and its description, known distributions, random vector, function of random variable. Methods of point estimates	nate beams and sin	nple girders. al characteristic 5 tical hypothesi
Principle of virtual wof planar shapes. F611STAS Definition of probab Regression and cormultiple regression	orce's in plane and space. Calculation of reactions of bodies and structures. Assessment of internal forces on statically determined. Kinematic method for calculation of reactions of statically determinate systems. Determination of axial forces in truss construct ber polygons and chains.  Statistics  Ity, random variable and its description, known distributions, random vector, function of random variable. Methods of point estimate relation, linear regression, correlation coefficient, coefficient of determination, the general linear model, statistical inference in line	nate beams and sin	nple girders. al characteristic 5 tical hypothesi
Principle of virtual worf planar shapes. Fig. 11STAS Definition of probabe Regression and comultiple regression 617TEDK	orces in plane and space. Calculation of reactions of bodies and structures. Assessment of internal forces on statically determined. Kinematic method for calculation of reactions of statically determinate systems. Determination of axial forces in truss construct ber polygons and chains.  Statistics  Ity, random variable and its description, known distributions, random vector, function of random variable. Methods of point estimate relation, linear regression, correlation coefficient, coefficient of determination, the general linear model, statistical inference in line the use of matrices in regression.	nate beams and sinitions. Cross-sectional  Z,ZK  tion. Testing of statisear regression, anal	nple girders. al characteristic  5 tical hypothesi ysis of varianc
Principle of virtual wof planar shapes. Feb 11STAS Definition of probabe Regression and comultiple regression 617TEDK Basic terms in trans	orce's in plane and space. Calculation of reactions of bodies and structures. Assessment of internal forces on statically determined. Kinematic method for calculation of reactions of statically determinate systems. Determination of axial forces in truss construct ber polygons and chains.  Statistics  lity, random variable and its description, known distributions, random vector, function of random variable. Methods of point estimate relation, linear regression, correlation coefficient, coefficient of determination, the general linear model, statistical inference in line the use of matrices in regression.  Transport Technology and Logistics	nate beams and similar in the second	nple girders. al characteristic  5 tical hypothesi ysis of varianc  4 ation of traffic i
Principle of virtual wof planar shapes. F 611STAS Definition of probab Regression and comultiple regression 617TEDK Basic terms in trans	orce's in plane and space. Calculation of reactions of bodies and structures. Assessment of internal forces on statically determined. Kinematic method for calculation of reactions of statically determinate systems. Determination of axial forces in truss construct ber polygons and chains.  Statistics  Ity, random variable and its description, known distributions, random vector, function of random variable. Methods of point estimate relation, linear regression, correlation coefficient, coefficient of determination, the general linear model, statistical inference in line the use of matrices in regression.  Transport Technology and Logistics port technology and logistics, particular steps of transport planning, line planning, timetabling, planning in pasanger and freight	nate beams and similar in the second	nple girders. al characteristic  5 tical hypothesi ysis of varianc  4 ation of traffic i

Flight planning, optimization of speed and heights, minimum fuel. Limitations of operation, maintenance, service life of aircraft. Traffic management, ground handling, security. Air crew.

612215	Railway Lines and Stations	Z,ZK	4
Rail transport. Railway t	rack geometry parameters. Route layout of railway lines. Railway line construction - railway substructure and superstructure.	Spatial layout of ra	ailway lines.
Pailway control systems	s in relation to infrastructure. Operating and carriage points. Pailway lines net and category Traction in rail transport		

List of courses of this pass:

Code	Name of the course	Completion	Credits
611CAL1	Calculus 1	Z,ZK	7
Sequence of real n	umbers and its limit. Basic properties of mappings. Function of one real variable, its limit and derivative. Geometric properties of n-dim		n space an
Cartesi	an coordinate system. Geometric meaning of the differential of functions several real variables, differential calculus of functions of se	veral real variables	
611CAL2	Calculus 2	Z,ZK	5
	ewtonian integral, Riemannian integral of the function of one variable, improper Riemannian integral, Riemannian integral in Rn. Para	•	_
k-dimensional su	rfaces in Rn, Riemannian integral over regular surfaces. Line and surface integrals of the second type, Stokes theorems, ordinary dif	erential equations	of the first
	order, linear differential equations with constant coefficients and its systems.		1
611FY1	Physics 1	Z,ZK	4
	natics, particle dynamics, dynamics of particle systems and rigid body. Continuum mechanics, thermodynamics, electric field, directe		
611GIE	Geometry	KZ	3
0 1	d oblique projections, linear perspective. Topographic surfaces and their orthogonal projection. Differential geometry of curves - param	,	,
	and curvature, Frenet's trihedron. Kinematics - a curve as a trajectory of the motion, the velocity and acceleration of a particle movin		
611LA	Linear Algebra	Z,ZK	3
Vector spaces (line	ear combinations, linear independence, dimension, basis, coordinates). Matrices and operations. Systems of linear equations and the	· ·	minants an
0.1.1.0.7.1.0	their applications. Scalar product. Similarity of matrices (eigenvalues and eigenvectors). Quadratic forms and their classificat		
611STAS	Statistics	Z,ZK	5
•	oility, random variable and its description, known distributions, random vector, function of random variable. Methods of point estimation.	0	, ·
Regression and co	rrelation, linear regression, correlation coefficient, coefficient of determination, the general linear model, statistical inference in linear re multiple regression, the use of matrices in regression.	gression, analysis	oi variance
612ZTS		Z,ZK	4
	Railway Lines and Stations ailway track geometry parameters. Route layout of railway lines. Railway line construction - railway substructure and superstructure. \$	'	
itali tialisport. Ita	Railway control systems in relation to infrastructure. Operating and carriage points. Railway lines net and category. Traction in rail t		way iii les.
612ZYDK	Introduction to Transportation Engineering	Z,ZK	3
	ion in land-use planning. Basic terms in transportation engineering. Traffic survey and traffic prognosis. Introduction to topic of roads, p		_
rtolo of transportat	impacts of transportation to environment and safety.	abile made transpe	or a reogaliv
614AS	Algorithm and Data Structures	KZ	2
	niliarized with selected basic and derived data structures, algorithms, their properties and their design procedure. Students will analyze		I
	et task and the resulting algorithm write by means of flowcharts, practice in reading algorithms recorded by means of the flowchart a		
	algebra with forming the conditions for the algorithms.		J. 200.0a
614PRG	Programming	KZ	2
-	pment, methods of structured programming, high-level programming languages, basics of C programming languages (types, variable		_
<b>3</b>	functions), programming techniques, complexity.	.,,.,.,	, - · · · <b>,</b> - ,
616UDOP	Introduction into Vehicles	Z	2
	portation systems. Functionality and setup. Movement and drive principles. Engines and their characteristics. Rail, road, air and wate	_	_
	of transport. Lifting equipment and conveyors. Legislation.	·	
617TEDK	Transport Technology and Logistics	KZ	4
	sport technology and logistics, particular steps of transport planning, line planning, timetabling, planning in pasanger and freight trar		of traffic in
each transport m	odus, technologic factors of the side of operator and client, organisation of city transport, logistic technologies and their aplication us	ing various transpo	ort modus.
618MTY	Materials Science and Engineering	Z,ZK	3
	terials science and engineering explains mechanical properties of structural materials based on their bonding forces and microstructu		I
is paid to metals as	s the most important engineering materials, also other major classes of materials are presented, namely ceramics, polymers and cor	nposites. Attention	is also paid
	to degradation processes in materials, to defectoscopy and to main mechanical tests.		
618SAT	Structural Analysis	Z,ZK	4
General system	of forces in plane and space. Calculation of reactions of bodies and structures. Assessment of internal forces on statically determinat	e beams and simp	le girders.
Principle of virtual v	vork. Kinematic method for calculation of reactions of statically determinate systems. Determination of axial forces in truss constructions.	Cross-sectional ch	aracteristic
	of planar shapes. Fiber polygons and chains.		
618TED	Technical Documentation	KZ	2
Technical standa	irds, international standardization, technical drawings, representation of technical objects, technical diagrams and charts, dimensional	al and geometrical	accuracy,
	arrangement of drawing sheets.	т	1
620SYSA	Systems Analysis	Z,ZK	5
-	em sciences, system viewpoint, terminology, typical system analysis tasks, system identification, system interface and interface tasks		
and its analysis,	strong functions and processes, genetic code, system identity, system architecture. Tools for system analysis - Petri nets, decision tal	oles, algorithms for	structural
	tasks. Soft and hard systems, methods for soft system analysis.		1
621ZALD	Basics of Air Transport	KZ	2
-	terminology, basic rules. VFR/IFR. Basics of aerodynamics. Propulsion of aircraft. Aircraft design. Basics of navigation, radio navigation.		
Flight planning, op	timization of speed and heights, minimum fuel. Limitations of operation, maintenance, service life of aircraft. Traffic management, ground Airlines and economics. Space technologies.	nd handling, secur	rity. Air crev

For updated information see <a href="http://bilakniha.cvut.cz/en/FF.html">http://bilakniha.cvut.cz/en/FF.html</a>

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