Study plan

Name of study plan: navaz. mag. PRE program IS v CZ 23/24

Faculty/Institute/Others:

Department:

Branch of study guaranteed by the department: Welcome page

Garantor of the study branch:

Program of study: Intelligent Transport Systems

Type of study: Follow-up master full-time

Required credits: 76

Elective courses credits: 44 Sum of credits in the plan: 120

Note on the plan:

Name of the block: Semestrální projekt Minimal number of credits of the block: 27

The role of the block: ZP

Code of the group: XN IS CZ 1-4 20/21

Name of the group: Projekty nav.prez.1.-4.sem (od) 20/21 programu IS v CZ Requirement credits in the group: In this group you have to gain 27 credits

Requirement courses in the group: In this group you have to complete 4 courses

Credits in the group: 27 Note on the group:

| Code | Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) | Completion | Credits | Scope | Semester | Role |
|--------|---|------------|---------|-------|----------|------|
| 11XN1S | Tutors, authors and guarantors (gar.) Master project 1 for study programme IS | Z | 5 | 0P+4C | Z | ZP |
| 12XN1S | Master project 1 for study programme IS | Z | 5 | 0P+4C | Z | ZP |
| 14XN1S | Master project 1 for study programme IS Zden k Lokaj, Martin Šrotý , Tomáš Zelinka | Z | 5 | 0P+4C | Z | ZP |
| 15XN1S | Master project 1 for study programme IS | Z | 5 | 0P+4C | Z | ZP |
| 16XN1S | Master project 1 for study programme IS | Z | 5 | 0P+4C | Z | ZP |
| 17XN1S | Master project 1 for study programme IS | Z | 5 | 0P+4C | Z | ZP |
| 18XN1S | Master project 1 for study programme IS | Z | 5 | 0P+4C | Z | ZP |
| 20XN1S | Master project 1 for study programme IS Ji I R ži ka | Z | 5 | 0P+4C | Z | ZP |
| 21XN1S | Master project 1 for study programme IS | Z | 5 | 0P+4C | Z | ZP |
| 22XN1S | Master project 1 for study programme IS | Z | 5 | 0P+4C | Z | ZP |
| 23XN1S | Master project 1 for study programme IS | Z | 5 | 0P+4C | Z | ZP |
| 11XN2S | Master project 2 for study programme IS | Z | 6 | 0P+4C | L | ZP |
| 12XN2S | Master project 2 for study programme IS | Z | 6 | 0P+4C | L | ZP |
| 14XN2S | Master project 2 for study programme IS Vít Fábera Vít Fábera (Gar.) | Z | 6 | 0P+4C | L | ZP |
| 15XN2S | Master project 2 for study programme IS | Z | 6 | 0P+4C | L | ZP |
| 16XN2S | Master project 2 for study programme IS | Z | 6 | 0P+4C | L | ZP |
| 17XN2S | Master project 2 for study programme IS | Z | 6 | 0P+4C | L | ZP |
| 18XN2S | Master project 2 for study programme IS | Z | 6 | 0P+4C | L | ZP |
| 20XN2S | Master project 2 for study programme IS Martin Leso | Z | 6 | 0P+4C | L | ZP |
| 21XN2S | Master project 2 for study programme IS | Z | 6 | 0P+4C | L | ZP |
| 22XN2S | Master project 2 for study programme IS | Z | 6 | 0P+4C | L | ZP |
| 23XN2S | Master project 2 for study programme IS | Z | 6 | 0P+4C | L | ZP |
| 11XN3S | Master project 3 for study programme IS | Z | 6 | 0P+4C | Z | ZP |

| 12XN3S | Master project 3 for study programme IS | Z | 6 | 0P+4C | Z | ZP |
|--------|---|---|----|-------|---|----|
| 14XN3S | Master project 3 for study programme IS Zden k Lokaj, Martin Šrotý, Tomáš Zelinka, Vít Fábera | Z | 6 | 0P+4C | Z | ZP |
| 15XN3S | Master project 3 for study programme IS | Z | 6 | 0P+4C | Z | ZP |
| 16XN3S | Master project 3 for study programme IS Josef Mík, Dmitry Rozhdestvenskiy, Petr Bouchner | Z | 6 | 0P+4C | Z | ZP |
| 17XN3S | Master project 3 for study programme IS | Z | 6 | 0P+4C | Z | ZP |
| 18XN3S | Master project 3 for study programme IS | Z | 6 | 0P+4C | Z | ZP |
| 20XN3S | Master project 3 for study programme IS Ji í R ži ka, Milan Sliacky | Z | 6 | 0P+4C | Z | ZP |
| 21XN3S | Master project 3 for study programme IS | Z | 6 | 0P+4C | Z | ZP |
| 22XN3S | Master project 3 for study programme IS | Z | 6 | 0P+4C | Z | ZP |
| 23XN3S | Master project 3 for study programme IS | Z | 6 | 0P+4C | Z | ZP |
| 11XN4S | Master project 4 for study programme IS | Z | 10 | 0P+8C | L | ZP |
| 12XN4S | Master project 4 for study programme IS | Z | 10 | 0P+8C | L | ZP |
| 14XN4S | Master project 4 for study programme IS Zden k Lokaj, Martin Šrotý, Tomáš Zelinka, Vít Fábera, Jan Zelenka | Z | 10 | 0P+8C | L | ZP |
| 15XN4S | Master project 4 for study programme IS | Z | 10 | 0P+8C | L | ZP |
| 16XN4S | Master project 4 for study programme IS Josef Mik, Petr Bouchner | Z | 10 | 0P+8C | L | ZP |
| 17XN4S | Master project 4 for study programme IS | Z | 10 | 0P+8C | L | ZP |
| 18XN4S | Master project 4 for study programme IS | Z | 10 | 0P+8C | L | ZP |
| 20XN4S | Master project 4 for study programme IS Milan Sliacky | Z | 10 | 0P+8C | L | ZP |
| 21XN4S | Master project 4 for study programme IS | Z | 10 | 0P+8C | L | ZP |
| 22XN4S | Master project 4 for study programme IS | Z | 10 | 0P+8C | L | ZP |
| 23XN4S | Master project 4 for study programme IS | Z | 10 | 0P+8C | L | ZP |
| | | | | | | |

Characteristics of the courses of this group of Study Plan: Code=XN IS CZ 1-4 20/21 Name=Projekty nav.prez.1.-4.sem (od) 20/21 programu IS v CZ

| programu is v Cz | | | |
|------------------|---|---|----|
| 11XN1S | Master project 1 for study programme IS | Z | 5 |
| 12XN1S | Master project 1 for study programme IS | Z | 5 |
| 14XN1S | Master project 1 for study programme IS | Z | 5 |
| 15XN1S | Master project 1 for study programme IS | Z | 5 |
| 16XN1S | Master project 1 for study programme IS | Z | 5 |
| 17XN1S | Master project 1 for study programme IS | Z | 5 |
| 18XN1S | Master project 1 for study programme IS | Z | 5 |
| 20XN1S | Master project 1 for study programme IS | Z | 5 |
| 21XN1S | Master project 1 for study programme IS | Z | 5 |
| 22XN1S | Master project 1 for study programme IS | Z | 5 |
| 23XN1S | Master project 1 for study programme IS | Z | 5 |
| 11XN2S | Master project 2 for study programme IS | Z | 6 |
| 12XN2S | Master project 2 for study programme IS | Z | 6 |
| 14XN2S | Master project 2 for study programme IS | Z | 6 |
| 15XN2S | Master project 2 for study programme IS | Z | 6 |
| 16XN2S | Master project 2 for study programme IS | Z | 6 |
| 17XN2S | Master project 2 for study programme IS | Z | 6 |
| 18XN2S | Master project 2 for study programme IS | Z | 6 |
| 20XN2S | Master project 2 for study programme IS | Z | 6 |
| 21XN2S | Master project 2 for study programme IS | Z | 6 |
| 22XN2S | Master project 2 for study programme IS | Z | 6 |
| 23XN2S | Master project 2 for study programme IS | Z | 6 |
| 11XN3S | Master project 3 for study programme IS | Z | 6 |
| 12XN3S | Master project 3 for study programme IS | Z | 6 |
| 14XN3S | Master project 3 for study programme IS | Z | 6 |
| 15XN3S | Master project 3 for study programme IS | Z | 6 |
| 16XN3S | Master project 3 for study programme IS | Z | 6 |
| 17XN3S | Master project 3 for study programme IS | Z | 6 |
| 18XN3S | Master project 3 for study programme IS | Z | 6 |
| 20XN3S | Master project 3 for study programme IS | Z | 6 |
| 21XN3S | Master project 3 for study programme IS | Z | 6 |
| 22XN3S | Master project 3 for study programme IS | Z | 6 |
| 23XN3S | Master project 3 for study programme IS | Z | 6 |
| 11XN4S | Master project 4 for study programme IS | Z | 10 |
| | | | |

| 12XN4S | Master project 4 for study programme IS | Z | 10 |
|--------|---|---|----|
| 14XN4S | Master project 4 for study programme IS | Z | 10 |
| 15XN4S | Master project 4 for study programme IS | Z | 10 |
| 16XN4S | Master project 4 for study programme IS | Z | 10 |
| 17XN4S | Master project 4 for study programme IS | Z | 10 |
| 18XN4S | Master project 4 for study programme IS | Z | 10 |
| 20XN4S | Master project 4 for study programme IS | Z | 10 |
| 21XN4S | Master project 4 for study programme IS | Z | 10 |
| 22XN4S | Master project 4 for study programme IS | Z | 10 |
| 23XN4S | Master project 4 for study programme IS | Z | 10 |

Name of the block: Compulsory courses Minimal number of credits of the block: 49

The role of the block: Z

Code of the group: 1.S.NPIS CZ 20/21

Name of the group: 1.sem.nav.prez (od) 20/21 - program IS v CZ

Requirement credits in the group: In this group you have to gain 22 credits

Requirement courses in the group: In this group you have to complete 5 courses

Credits in the group: 22 Note on the group:

| Code | Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.) | Completion | Credits | Scope | Semester | Role |
|--------|---|------------|---------|-------|----------|------|
| 11MAI | ITS Mathematical Tools Jan P ikryl Jan P ikryl Jan P ikryl (Gar.) | Z,ZK | 4 | 2P+2C | Z | Z |
| 16DITS | Vehicles within ITS David Lehet, Jaroslav Machan | Z,ZK | 4 | 2P+2C | Z | Z |
| 20GINS | Geographical, information, localization and navigation systems Pavel Hrubeš, Petr Bureš, Zuzana Purkrábková, František Kekula | Z,ZK | 6 | 3P+3C | Z | Z |
| 20TSJ | Telematic systems and their design Pavel Hrubeš, Martin Langr | Z,ZK | 6 | 3P+2C | Z | Z |
| 23TBSS | Technology and Security of Sensor Networks Václav Jirovský Václav Jirovský (Gar.) | KZ | 2 | 2P+0C | Z | Z |

Characteristics of the courses of this group of Study Plan: Code=1.S.NPIS CZ 20/21 Name=1.sem.nav.prez (od) 20/21 - program IS v

| 11MAI | ITS Mathematical Tools | ∠,∠K | 4 |
|---------------------------|--|-----------------------|-----------------|
| Series, Fourier Series | Discrete Fourier Transform. Segmentation of signals, windows, localization. Short-term Fourier Transform. From Fourier Analy | sis to PDE. Fund | amentals of |
| Numerical Mathematic | s. Numerical solutions to ODEs and PDEs. Continuous traffic flow models described by PDE. Car-following models as ODEs. | | |
| 16DITS | Vehicles within ITS | Z,ZK | 4 |
| Design of the vehicle | vith focus on its use and function in frame of ITS. User requirement analyses. Economic aspects. Process of constructions in a | a concept phase, | functional |
| dependences and stru | cture of the designed object. Creation of functional models. Energy management and storages for ground vehicles, energy tra | nsformations lead | ling to kinetic |
| one. Propulsion system | ns / traditional and alternative ones. Life-cycle analysis. | | |
| 20GINS | Geographical, information, localization and navigation systems | Z,ZK | 6 |
| The subject is specialize | ed in problems of work with applications of geographic information systems with special attention to the specialization in the field o | f transport and tel | ecommunication. |
| It introduces students | to geographic data management practices and tools, real world modeling, geographic data storage models, data entry and dig | jitization methods | , and a number |
| of other GIS related to | chnologies such as problem mapping, webmap, etc. | | |
| 20TSJ | Telematic systems and their design | Z,ZK | 6 |
| Gradual detailed analy | rsis of individual existing telematics systems in modes of transport, such as toll systems, vehicle weighing, fleet management, | traffic manageme | ent, etc. |
| 23TBSS | Technology and Security of Sensor Networks | KZ | 2 |
| The course focuses of | the safety of data collection in new areas of sensor networks. Principles of sensor networks, sensors of electrical and non-ele | ectric quantities, in | nterfaces for |
| sensor connection, co | mmunication technology for sensor networks, SigFox, LoRa, NB-IoT, IoT technology and SmartCity. Trends in IoT and Smart C | City | |

Code of the group: 1.S.NPIS VYBCZ 20/21

Name of the group: 1.sem.nav.prez (od) 20/21 výb r p edm tu - program IS v CZ

Requirement credits in the group: In this group you have to gain 3 credits

Requirement courses in the group: In this group you have to complete 1 course

Credits in the group: 3 Note on the group:

| Code | Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.) | Completion | Credits | Scope | Semester | Role |
|--------|---|------------|---------|-------|----------|------|
| 12TDP | Traffic Flow Theory Vladimír Faltus | Z,ZK | 3 | 2P+1C | Z | Z |
| 16ESDP | Electronic systems in modern vehicles Petr Bouchner, Dmitrij Rožd stvenský | Z,ZK | 3 | 2P+1C | Z | Z |
| 20MZZ | Modern techniques of safety control of moving railway vehicles Martin Leso | Z,ZK | 3 | 2P+1C | Z | Z |

Characteristics of the courses of this group of Study Plan: Code=1.S.NPIS VYBCZ 20/21 Name=1.sem.nav.prez (od) 20/21 výb r p edm tu - program IS v CZ

12TDP Traffic Flow Theory Z,ZK 3

Mobility and associated human problems. Basic traffic parameters and their measurement. Estimation of quality of services. Theoretical fundamentals and applications of mathematical models. Macroscopic, statistical and microscopic models. Theory of shock waves, queuing theory and special theory of traffic phenomena. Relation between traffic models and traffic flow management.

16ESDP Electronic systems in modern vehicles

Z,ZK

| 3

Advanced vehicle systems, electromobility, V2I and V2V, autonomous driving. Combustion engine control and electronic control units. Electric propulsion, its components, basic characteristics and control. Management of hybrid propulsion for attaining its optimal efficiency. Vehicle communication bus (CAN, LIN, FlexRay etc.). Safety, communication and comfort electronic vehicle systems. Practical exercises with real and simulated systems.

20MZZ Modern techniques of safety control of moving railway vehicles

.ZK

3

ERTMS / ETCS concepts, ETCS architecture and interface descriptions, ERTMS system level, infrastructure and mobile part of the system, linking to stationary security systems, operating and application modes of the system, infrastructure orientation, interface (DMI), integration of the ETCS mobile part into the driving vehicle, GSM-R functional specification, testing and legislation.

Code of the group: 2.S.NPIS CZ 20/21

Name of the group: 2.sem.nav.prez (od) 20/21 - program IS v CZ

Requirement credits in the group: In this group you have to gain 21 credits

Requirement courses in the group: In this group you have to complete 5 courses

Credits in the group: 21 Note on the group:

| Code | Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.) | Completion | Credits | Scope | Semester | Role |
|--------|---|------------|---------|-------|----------|------|
| 14CITS | C-ITS Systems Zden k Lokaj, Tomáš Zelinka, Miroslav Vaniš Zden k Lokaj Zden k Lokaj (Gar.) | Z,ZK | 6 | 3P+3C | L | Z |
| 14PAM | Programming and modelling Vít Fábera, Tomáš Brandejský, Marek Kalika, Martin Fiala Vít Fábera Vít Fábera (Gar.) | Z,ZK | 4 | 2P+2C | L | Z |
| 14PD | Data processing Martin Šrotý , Miroslav Vaniš Martin Šrotý Martin Šrotý (Gar.) | Z,ZK | 6 | 2P+4C | L | Z |
| 14PPRP | Computer Aided Project Management Marek Kalika Marek Kalika Marek Kalika (Gar.) | KZ | 2 | 0P+2C | L | Z |
| 20BITS | Safety and reliability of ITS Systems Vladimír Faltus, Tomáš Tichý | KZ | 3 | 2P+1C | L | Z |

Characteristics of the courses of this group of Study Plan: Code=2.S.NPIS CZ 20/21 Name=2.sem.nav.prez (od) 20/21 - program IS v CZ

14CITS | C-ITS Systems | Z,ZK | 6 |
Detailed description of C-ITS systems architecture, description of use-cases - urban and rural applications, principles of C-ITS funcionality with focus on data exchange (CAM, DENM, IVI) and C-ITS security architecture. Status quo and modern trends of wireless telecommunication solutions ITS-G5 and LTE-V and description of its properties and specifics. Course will also cover signal processing.

14PAM Programming and modelling

Z,ZK

. 4

Object oriented programming, dynamic memory allocation, inheritage, generic programming, STL, abstract data types, programming techniques, recursion, complexity, Lindenmeyer's grammars, paralism in nature and in real systems, paralel computer systems, paralel programming, discrete simulation, models of processes, model types As-Is a To-Be, acquisition of analytical sources for modelling, BPMN language, SW Bizagi, model creation and life cycle.

14PD Data processing

Z,ZK

6

Students will learn about tools for data processing and analysis, using practical examples to try out the most common options used in data processing, including advanced options for presenting the results of analyses. In advanced methods, students will also perform specific analysis using Bayesian networks. Students will then independently perform data analysis on data from existing open systems.

14PPRP Computer Aided Project Management

KZ

2

What is the project? The basic terms a concepts of project management. Life cycle of the project and its phased approach. Analysis and specification of the assignment, activity definition, stages, objectives and measurability. Risk events and risk planning. Project change management during implementation. Preparation of the project outline (activities, restrictions, assignments, calendars etc.) Project planning and optimization - time, resources.

20BITS Safety and reliability of ITS Systems

ΚZ

3

The basic concepts of safety and reliability in the job and application. Basic schema and types of diagnostic systems including reliability diagnostics of technical equipment and ITS. Investigation of acceptability and reliability prediction, traffic crity and sensitivity analysis. Neural Networks and other optimization algorithms and ETA, FMEA failure analysis. HMI in traffic including operator testing on simulator and in real-world situatiation

Code of the group: 2.S.NPIS VYBCZ 20/21

Name of the group: 2.sem.nav.prez (od) 20/21 výb r p edm tu - program IS v CZ

Requirement credits in the group: In this group you have to gain 3 credits

Requirement courses in the group: In this group you have to complete 1 course

Credits in the group: 3 Note on the group:

| Code | Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.) | Completion | Credits | Scope | Semester | Role |
|--------|---|------------|---------|-------|----------|------|
| 14MIM | Microsimulation Models Jan Kr ál Jan Kr ál Jan Kr ál (Gar.) | KZ | 3 | 0P+3C | L | Z |
| 16SHMI | Simulation and HMI Stanislav Novotný, Tereza Kunclová, Michal Cenkner | Z,ZK | 3 | 2P+1C | L | Z |
| 20ITSR | ITS - R Martin Leso Martin Leso (Gar.) | Z,ZK | 3 | 2P+1C | L | Z |

Characteristics of the courses of this group of Study Plan: Code=2.S.NPIS VYBCZ 20/21 Name=2.sem.nav.prez (od) 20/21 výb r p edm tu - program IS v CZ

| 14MIM | Microsimulation Models | KZ | 3 |
|-----------------------------|---|---------------------|-------------------|
| Basic knowledge of traf | ic modeling and simulation will be broaded by the application of traffic control algorithms to traffic microsimulation models us | ed in ITS. These | include, for |
| example, the proposal o | f algorithms for actuated signal control, pedestrian preference, dynamic network routing, road line traffic control, crossing secur | rity equipment, and | d PT preference. |
| Algorithms will be desig | ned, applied, and tested by students themselves. | | |
| 16SHMI | Simulation and HMI | Z,ZK | 3 |
| Simulation for the system | ns in transportation and vehicle systems. User interface, HMI (human-machine interaction), virtual reality and computer graph | nics for ITS. Simul | ation theory with |
| application of computing | g equipment. Creating computing models. Mechanic and dynamic systems and their mathematical models. Simulation of vehi | icle dynamics, on- | -land carriage in |
| particular. Virtual reality | systems. | | |
| 20ITSR | ITS - R | Z,ZK | 3 |
| The introduction is devo | ted to description of the architecture and interface of the system with the ITS-R concept, the communication interface of the | system, principles | s of ensuring |
| functional and security f | eatures are defined. The principles of ERTMS / ETCS application level 3, UGTMS, CBTC are discussed in detail. Current and fu | uture communicat | ion technologies |
| are described. | | | |

List of courses of this pass:

| Code | Name of the course | Completion | Credits |
|----------------------|--|---------------------|---------------|
| 11MAI | ITS Mathematical Tools | Z,ZK | 4 |
| Series, Fourier | Series. Discrete Fourier Transform. Segmentation of signals, windows, localization. Short-term Fourier Transform. From Fourier Analys | sis to PDE. Fundan | nentals of |
| ٨ | lumerical Mathematics. Numerical solutions to ODEs and PDEs. Continuous traffic flow models described by PDE. Car-following mod | els as ODEs. | |
| 11XN1S | Master project 1 for study programme IS | Z | 5 |
| 11XN2S | Master project 2 for study programme IS | Z | 6 |
| 11XN3S | Master project 3 for study programme IS | Z | 6 |
| 11XN4S | Master project 4 for study programme IS | Z | 10 |
| 12TDP | Traffic Flow Theory | Z,ZK | 3 |
| • | iated human problems. Basic traffic parameters and their measurement. Estimation of quality of services. Theoretical fundamentals an | | |
| models. Macrosco | pic, statistical and microscopic models. Theory of shock waves, queuing theory and special theory of traffic phenomena. Relation bet | ween traffic model | s and traffic |
| 40)/1140 | flow management. | _ | |
| 12XN1S | Master project 1 for study programme IS | Z | 5 |
| 12XN2S | Master project 2 for study programme IS | Z | 6 |
| 12XN3S | Master project 3 for study programme IS | Z | 6 |
| 12XN4S | Master project 4 for study programme IS | Z | 10 |
| 14CITS | C-ITS Systems | Z,ZK | 6 |
| Detailed description | n of C-ITS systems architecture, description of use-cases - urban and rural applications, principles of C-ITS funcionality with focus on | data exchange (C | AM, DENN |
| IVI) and C-ITS sec | curity architecture. Status quo and modern trends of wireless telecommunication solutions ITS-G5 and LTE-V and description of its pr | operties and speci | fics. Course |
| | will also cover signal processing. | | |
| 14MIM | Microsimulation Models | KZ | 3 |
| Basic knowledg | e of traffic modeling and simulation will be broaded by the application of traffic control algorithms to traffic microsimulation models us | ed in ITS. These in | clude, for |
| example, the propo | osal of algorithms for actuated signal control, pedestrian preference, dynamic network routing, road line traffic control, crossing security | equipment, and PT | preference |
| | Algorithms will be designed, applied, and tested by students themselves. | | |
| 14PAM | Programming and modelling | Z,ZK | 4 |
| | ogramming, dynamic memory allocation, inheritage, generic programming, STL, abstract data types, programming techniques, recurs | | |
| grammars, paralis | m in nature and in real systems, paralel computer systems, paralel programming, discrete simulation, models of processes, model ty | pes As-Is a To-Be, | acquisition |

of analytical sources for modelling, BPMN language, SW Bizagi, model creation and life cycle.

| 14PD | Data processing | Z,ZK | 6 |
|---|---|--|---|
| | ut tools for data processing and analysis, using practical examples to try out the most common options used in data processing, in | • | • |
| esenting the results | of analyses. In advanced methods, students will also perform specific analysis using Bayesian networks. Students will then indeper | ndently perform | data analy |
| | on data from existing open systems. | | |
| 14PPRP | Computer Aided Project Management | KZ | 2 |
| | The basic terms a concepts of project management. Life cycle of the project and its phased approach. Analysis and specification bjectives and measurability. Risk events and risk planning. Project change management during implementation. Preparation of the | | |
| definition, stages, t | restrictions, assignments, calendars etc.) Project planning and optimization - time, resources. | project outline | activities, |
| 14XN1S | Master project 1 for study programme IS | Z | 5 |
| 14XN2S | Master project 2 for study programme IS | Z | 6 |
| 14XN3S | Master project 2 for study programme IS Master project 3 for study programme IS | Z | 6 |
| 14XN4S | Master project 3 for study programme IS Master project 4 for study programme IS | Z | 10 |
| 15XN1S | Master project 4 for study programme IS Master project 1 for study programme IS | Z | 5 |
| 15XN1S | Master project 1 for study programme IS Master project 2 for study programme IS | Z | 6 |
| 15XN3S | | Z | 6 |
| 15XN4S | Master project 3 for study programme IS | Z | 10 |
| | Master project 4 for study programme IS | | |
| 16DITS | Vehicles within ITS | Z,ZK | 4 |
| • | ucture of the designed object. Creation of functional models. Energy management and storages for ground vehicles, energy transf | | |
| pendences and st | one. Propulsion systems / traditional and alternative ones. Life-cycle analysis. | ormations icadii | ig to kinet |
| 16ESDP | Electronic systems in modern vehicles | Z,ZK | 3 |
| l l | ystems, electromobility, V2I and V2V, autonomous driving. Combustion engine control and electronic control units. Electric propulsi | | |
| | control. Management of hybrid propulsion for attaining its optimal efficiency. Vehicle communication bus (CAN, LIN, FlexRay etc.). S | - | |
| | comfort electronic vehicle systems. Practical exercises with real and simulated systems. | | |
| 16SHMI | Simulation and HMI | Z,ZK | 3 |
| - | ems in transportation and vehicle systems. User interface, HMI (human-machine interaction), virtual reality and computer graphics for | | - |
| olication of computing | ng equipment. Creating computing models. Mechanic and dynamic systems and their mathematical models. Simulation of vehicle of | dynamics, on-lar | d carriage |
| 4CVN14C | particular. Virtual reality systems. | 7 | |
| 16XN1S | Master project 1 for study programme IS | Z | 5 |
| 16XN2S | Master project 2 for study programme IS | Z | 6 |
| 16XN3S | Master project 3 for study programme IS | Z | 6 |
| 16XN4S | Master project 4 for study programme IS | Z | 10 |
| 17XN1S | Master project 1 for study programme IS | Z | 5 |
| 17XN2S | Master project 2 for study programme IS | Z | 6 |
| 17XN3S | Master project 3 for study programme IS | Z | 6 |
| 17XN4S | Master project 4 for study programme IS | Z | 10 |
| 18XN1S | Master project 1 for study programme IS | Z | 5 |
| 18XN2S | Master project 2 for study programme IS | Z | 6 |
| 18XN3S | Master project 3 for study programme IS | Z | 6 |
| 18XN4S | Master project 4 for study programme IS | Z | 10 |
| 20BITS | Safety and reliability of ITS Systems | KZ | 3 |
| | safety and reliability in the job and application. Basic schema and types of diagnostic systems including reliability diagnostics of te | echnical equipm | ent and IT |
| vestigation of accep | tability and reliability prediction, traffic crity and sensitivity analysis. Neural Networks and other optimization algorithms and ETA, F | MEA failure ana | lysis. HMI |
| | traffic including operator testing on simulator and in real-world situatiation | | |
| 20GINS | Geographical, information, localization and navigation systems | Z,ZK | 6 |
| - | ed in problems of work with applications of geographic information systems with special attention to the specialization in the field of tran | | |
| introduces students | to geographic data management practices and tools, real world modeling, geographic data storage models, data entry and digitiza | ition methods, a | nd a numl |
| | of other GIS related technologies such as problem mapping, webmap, etc. | | _ |
| 20ITSR | ITS - R | Z,ZK | 3 |
| ine introduction is a | evoted to description of the architecture and interface of the system with the ITS-R concept, the communication interface of the system with the ITS-R concept, the communication interface of the system are defined. The principles of ERTMS / ETCS application level 3, UGTMS, CBTC are discussed in detail. Current and future | | |
| | | Communication | recrinolog |
| | are described | | 3 |
| nctional and security | are described. | フフレ | - |
| nctional and security 20MZZ | Modern techniques of safety control of moving railway vehicles | Z,ZK | |
| ctional and security 20MZZ ERTMS / ETCS cond | | tationary securi | |
| actional and security 20MZZ ERTMS / ETCS cond | Modern techniques of safety control of moving railway vehicles epts, ETCS architecture and interface descriptions, ERTMS system level, infrastructure and mobile part of the system, linking to s | tationary securi | |
| ctional and security 20MZZ ERTMS / ETCS cond | Modern techniques of safety control of moving railway vehicles septs, ETCS architecture and interface descriptions, ERTMS system level, infrastructure and mobile part of the system, linking to so no modes of the system, infrastructure orientation, interface (DMI), integration of the ETCS mobile part into the driving vehicle, GS | tationary securi | |
| 20MZZ RTMS / ETCS concerating and applicate 20TSJ | Modern techniques of safety control of moving railway vehicles epts, ETCS architecture and interface descriptions, ERTMS system level, infrastructure and mobile part of the system, linking to so no modes of the system, infrastructure orientation, interface (DMI), integration of the ETCS mobile part into the driving vehicle, GS testing and legislation. | stationary securional Z,ZK | specificati |
| 20MZZ RTMS / ETCS conerating and applicate | Modern techniques of safety control of moving railway vehicles epts, ETCS architecture and interface descriptions, ERTMS system level, infrastructure and mobile part of the system, linking to s on modes of the system, infrastructure orientation, interface (DMI), integration of the ETCS mobile part into the driving vehicle, GS testing and legislation. Telematic systems and their design | stationary securional Z,ZK | specificat |
| 20MZZ RTMS / ETCS concerting and applicat 20TSJ Gradual detailed a | Modern techniques of safety control of moving railway vehicles septs, ETCS architecture and interface descriptions, ERTMS system level, infrastructure and mobile part of the system, linking to so no modes of the system, infrastructure orientation, interface (DMI), integration of the ETCS mobile part into the driving vehicle, GS testing and legislation. Telematic systems and their design nalysis of individual existing telematics systems in modes of transport, such as toll systems, vehicle weighing, fleet management, Master project 1 for study programme IS | stationary securi SM-R functional Z,ZK traffic managem | 6 nent, etc. |
| 20MZZ ERTMS / ETCS concerating and applicate 20TSJ Gradual detailed a 20XN1S 20XN2S | Modern techniques of safety control of moving railway vehicles septs, ETCS architecture and interface descriptions, ERTMS system level, infrastructure and mobile part of the system, linking to so no modes of the system, infrastructure orientation, interface (DMI), integration of the ETCS mobile part into the driving vehicle, GS testing and legislation. Telematic systems and their design nalysis of individual existing telematics systems in modes of transport, such as toll systems, vehicle weighing, fleet management, Master project 1 for study programme IS Master project 2 for study programme IS | stationary securi SM-R functional Z,ZK traffic managem Z Z | 6 nent, etc. |
| 20MZZ ERTMS / ETCS concerating and applicate 20TSJ Gradual detailed a 20XN1S 20XN2S 20XN3S | Modern techniques of safety control of moving railway vehicles septs, ETCS architecture and interface descriptions, ERTMS system level, infrastructure and mobile part of the system, linking to so no modes of the system, infrastructure orientation, interface (DMI), integration of the ETCS mobile part into the driving vehicle, GS testing and legislation. Telematic systems and their design nalysis of individual existing telematics systems in modes of transport, such as toll systems, vehicle weighing, fleet management, Master project 1 for study programme IS Master project 2 for study programme IS Master project 3 for study programme IS | stationary securi SM-R functional Z,ZK traffic managem Z Z Z | 6 eent, etc. 5 6 |
| 20MZZ ERTMS / ETCS concerating and applicat 20TSJ Gradual detailed at 20XN1S 20XN2S 20XN2S 20XN3S 20XN4S | Modern techniques of safety control of moving railway vehicles epts, ETCS architecture and interface descriptions, ERTMS system level, infrastructure and mobile part of the system, linking to so no modes of the system, infrastructure orientation, interface (DMI), integration of the ETCS mobile part into the driving vehicle, GS testing and legislation. Telematic systems and their design nalysis of individual existing telematics systems in modes of transport, such as toll systems, vehicle weighing, fleet management, Master project 1 for study programme IS Master project 2 for study programme IS Master project 3 for study programme IS Master project 4 for study programme IS Master project 4 for study programme IS | stationary securi SM-R functional Z,ZK traffic managem Z Z Z | 6 nent, etc. 5 6 6 10 |
| 20MZZ ERTMS / ETCS concerating and applicate 20TSJ Gradual detailed a 20XN1S 20XN2S 20XN3S 20XN4S 21XN1S | Modern techniques of safety control of moving railway vehicles epts, ETCS architecture and interface descriptions, ERTMS system level, infrastructure and mobile part of the system, linking to so no modes of the system, infrastructure orientation, interface (DMI), integration of the ETCS mobile part into the driving vehicle, GS testing and legislation. Telematic systems and their design nalysis of individual existing telematics systems in modes of transport, such as toll systems, vehicle weighing, fleet management, Master project 1 for study programme IS Master project 2 for study programme IS Master project 3 for study programme IS Master project 4 for study programme IS Master project 1 for study programme IS Master project 1 for study programme IS Master project 1 for study programme IS | tationary securi SM-R functional Z,ZK traffic managem Z Z Z Z | 6 eent, etc. 5 6 6 10 5 |
| 20MZZ ERTMS / ETCS concerating and applicate 20TSJ Gradual detailed at 20XN1S 20XN2S 20XN2S 20XN4S 21XN1S 21XN2S | Modern techniques of safety control of moving railway vehicles septs, ETCS architecture and interface descriptions, ERTMS system level, infrastructure and mobile part of the system, linking to so no modes of the system, infrastructure orientation, interface (DMI), integration of the ETCS mobile part into the driving vehicle, GS testing and legislation. Telematic systems and their design nalysis of individual existing telematics systems in modes of transport, such as toll systems, vehicle weighing, fleet management, Master project 1 for study programme IS Master project 2 for study programme IS Master project 3 for study programme IS Master project 4 for study programme IS Master project 1 for study programme IS Master project 2 for study programme IS | stationary securional Z,ZK traffic managem Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z | 6 eent, etc. 5 6 6 10 5 6 |
| 20MZZ ERTMS / ETCS concerating and applicate 20TSJ Gradual detailed a 20XN1S 20XN2S 20XN2S 20XN4S 21XN1S 21XN2S 21XN3S | Modern techniques of safety control of moving railway vehicles septs, ETCS architecture and interface descriptions, ERTMS system level, infrastructure and mobile part of the system, linking to so no modes of the system, infrastructure orientation, interface (DMI), integration of the ETCS mobile part into the driving vehicle, GS testing and legislation. Telematic systems and their design nalysis of individual existing telematics systems in modes of transport, such as toll systems, vehicle weighing, fleet management, Master project 1 for study programme IS Master project 2 for study programme IS Master project 3 for study programme IS Master project 4 for study programme IS Master project 1 for study programme IS Master project 2 for study programme IS Master project 2 for study programme IS Master project 3 for study programme IS | stationary securification and stationary securification and securifica | 6 eent, etc. 5 6 6 6 6 6 6 6 |
| 20MZZ ERTMS / ETCS concerating and applicate 20TSJ Gradual detailed a 20XN1S 20XN2S 20XN3S 20XN4S 21XN1S 21XN2S 21XN3S 21XN4S | Modern techniques of safety control of moving railway vehicles septs, ETCS architecture and interface descriptions, ERTMS system level, infrastructure and mobile part of the system, linking to so no modes of the system, infrastructure orientation, interface (DMI), integration of the ETCS mobile part into the driving vehicle, GS testing and legislation. Telematic systems and their design nalysis of individual existing telematics systems in modes of transport, such as toll systems, vehicle weighing, fleet management, Master project 1 for study programme IS Master project 2 for study programme IS Master project 3 for study programme IS Master project 4 for study programme IS Master project 1 for study programme IS Master project 2 for study programme IS Master project 2 for study programme IS Master project 3 for study programme IS Master project 4 for study programme IS | stationary securification and se | 6 eent, etc. 5 6 6 6 10 10 10 10 10 10 10 10 10 10 10 10 10 |
| 20MZZ ERTMS / ETCS concerating and applicat 20TSJ Gradual detailed at 20XN1S 20XN2S 20XN2S 20XN4S 21XN1S 21XN2S 21XN2S 21XN3S | Modern techniques of safety control of moving railway vehicles septs, ETCS architecture and interface descriptions, ERTMS system level, infrastructure and mobile part of the system, linking to so no modes of the system, infrastructure orientation, interface (DMI), integration of the ETCS mobile part into the driving vehicle, GS testing and legislation. Telematic systems and their design nalysis of individual existing telematics systems in modes of transport, such as toll systems, vehicle weighing, fleet management, Master project 1 for study programme IS Master project 2 for study programme IS Master project 3 for study programme IS Master project 4 for study programme IS Master project 1 for study programme IS Master project 2 for study programme IS Master project 2 for study programme IS Master project 3 for study programme IS | stationary securification and stationary securification and securifica | 6 eent, etc. 5 6 6 10 5 6 |

| 22XN3S | Master project 3 for study programme IS | Z | 6 |
|---|--|----|----|
| 22XN4S | Master project 4 for study programme IS | Z | 10 |
| 23TBSS | Technology and Security of Sensor Networks | KZ | 2 |
| The course focuses on the safety of data collection in new areas of sensor networks. Principles of sensor networks, sensors of electrical and non-electric quantities, interfaces for | | | |
| sensor connection, communication technology for sensor networks, SigFox, LoRa, NB-IoT, IoT technology and SmartCity. Trends in IoT and Smart City | | | |
| 23XN1S | Master project 1 for study programme IS | Z | 5 |
| 23XN2S | Master project 2 for study programme IS | Z | 6 |
| 23XN3S | Master project 3 for study programme IS | Z | 6 |
| 23XN4S | Master project 4 for study programme IS | Z | 10 |

For updated information see http://bilakniha.cvut.cz/en/FF.html Generated: day 2024-05-22, time 01:29.