Recomended pass through the study plan

Name of the pass: Branch Avionics - Passage through study

Faculty/Institute/Others: Faculty of Electrical Engineering Department: Pass through the study plan: Aerospace Engineering - study branch Avionics Branch of study guranteed by the department: Welcome page Guarantor of the study branch: Program of study: Aerospace Engineering Type of study: Follow-up master full-time Note on the pass:

Coding of roles of courses and groups of courses:

P - compulsory courses of the program, PO - compulsory courses of the branch, Z - compulsory courses, S - compulsory elective courses, PV - compulsory elective courses, F - elective specialized courses, V - elective courses, T - physical training courses

Coding of ways of completion of courses (KZ/Z/ZK) and coding of semesters (Z/L):

KZ - graded assesment, Z - assesment, ZK - examination, L - summer semester, Z - winter semester

Number of semes	ster: 1					
Code	Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.)	Completion	Credits	Scope	Semester	Role
BE9M38AML	Aerodynamika a mechanika letu Ji í Noži ka, Jakub Suchý Jan Rohá Ji í Noži ka (Gar.)	Z,ZK	6	2P+4L	Z	Р
BE9M38PSL	Aircraft Avionics Jan Rohá , Martin Šipoš Jan Rohá Jan Rohá (Gar.)	Z,ZK	6	2P+2L	Z	Р
BE9M04PRE	Presentation Skills Erik Peter Stadnik, Petra Jennings Petra Jennings (Gar.)	KZ	2	2C	Z	Р
BE9M38PRM	Project Management and Marketing Jan Rohá , Št pánka Uli ná, Petr Žemli ka Jan Rohá Jan Rohá (Gar.)	Z,ZK	2	2P+1C	Z	Р
BEEZM	Safety in Electrical Engineering for a master's degree Vladimír K la, Ivana Nová, Josef ernohous, Radek Havlí ek Radek Havlí ek Vladimír K la (Gar.)	Z	0	2BP+2BC	Z	Ρ
BE3M37KIN	Space Engineering Kristian Hengster-Movric, Václav Navrátil, Martin Hrom ík, René Hudec, Stanislav Vítek, Petr Ondrá ek, Martin Urban Stanislav Vítek René Hudec (Gar.)	Z,ZK	6	2P+2L	Z	Ρ
2016_MLAKEVOL	Elective subjects	Min. cours. 0	Min/Max 0/999			V

Number of seme	ster: 2					
Code	Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.)	Completion	Credits	Scope	Semester	Role
BE9M04AKP	Academic Writing Petra Jennings, Michael Ynsua Petra Jennings Petra Jennings (Gar.)	KZ	2	2C	L	Р
BE9M38INA	Integrated Modular Avionics Jan Rohá , Martin Šipoš Martin Šipoš (Gar.)	Z,ZK	6	2P+2L		Ρ
BE9M38TYP	Team Project Jan Rohá , Martin Šipoš Jan Rohá Martin Šipoš (Gar.)	KZ	6	0P+6C	L	Р
BE9M36BEP	Unmanned Vehicles Milan Rollo Milan Rollo (Gar.)	Z,ZK	4	2P+2L	L	Ρ
2016_MLAKEPV	Compulsory elective subjects of the programme AE0M37RLP,BE3M33ARO1, (see the list of groups below)	Min. cours. 2 Max. cours. 2	Min/Max 8/40			PV
2016_MLAKEVOL	Elective subjects	Min. cours. 0	Min/Max 0/999			V

Code	Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.)	Completion	Credits	Scope	Semester	Role
BE3M37LRS	Aeronautical Radio Systems Pavel Ková Pavel Ková Pavel Ková (Gar.)	Z,ZK	6	2P+2L	Z	Р
BE9M38POL	Aircraft Propulsion Jan Klesa Jan Klesa Jan Klesa (Gar.)	Z,ZK	5	3P+1C	Z	Р
BE9M38LKS	Aircraft Structures and Materials Robert Theiner Jan Rohá Robert Theiner (Gar.)	Z,ZK	5	3P+1C	Z	Р
BE9M35SRL	Flight Control Systems Martin Hrom ik Martin Hrom ik (Gar.)	Z,ZK	6	2P+2L	Z	Р
2016_MLAKEPV	Compulsory elective subjects of the programme AE0M37RLP,BE3M33AR01, (see the list of groups below)	Min. cours. 2 Max. cours. 2	Min/Max 8/40			PV
2016_MLAKEVOL	Elective subjects	Min. cours. 0	Min/Max 0/999			V

Number of semester: 4									
Code	Name of the course / Name of the group of courses (in case of groups of courses the list of codes of their members) Tutors, authors and guarantors (gar.)	Completion	Credits	Scope	Semester	Role			
BDIP30	Diploma Thesis	Z	30	22s	L	Р			

List of groups of courses of this pass with the complete content of members of individual groups

Kód		Name of the group ogroup (for specificat	of courses and ion see here o	codes of members of this r below the list of courses)	Com	pletion	Credit	s Scope	Semester	Role
					Min.	cours.				
2016_MLAKEPV		Compulsory elective subjects of the programme				2	Min/Ma	IX		PV
		Compulsory e	ective subject	cts of the programme		cours.	8/40			PV
						2				
AE0M37RLP	Air traffic c	ontrol	BE3M33ARO1	Autonomous Robotics		BE9M35OFD Estimation, Filtering and Dete			ect	
BE9M38EML	Experimen	tální metody v letectví	BE1M13JAS1	Quality and Reliability		BE2M37RNVA Radio Navigation				
BE2M37SSPA	Statistical	Signal Processing	BE9M38VBM	Videometry and Contactless Meas	u	1				
					Min.	cours.	Min/Ma	IX		
2016_MLAKEVOL			Elective subjects			0	0/999			v

List of courses of this pass:

Code	Name of the course	Completion	Credits
AE0M37RLP	Air traffic control	Z,ZK	4
Air traffic control	service and its function. Air traffic control procedures and utilization of the communication, navigation and radar systems. Requireme	nts on radio equip	ment. The
	course applies knowledge from course Navigation. The knowledge is applicable in aerospace industry and air business.		
BDIP30	Diploma Thesis	Z	30
Independent final	comprehensive work for the Master's degree study programme. A student will choose a topic from a range of topics related to his or l	her branch of study	, which will
be specified b	y branch department or branch departments. The diploma thesis will be defended in front of the board of examiners for the compreh	ensive final examir	nation.
BE1M13JAS1	Quality and Reliability	Z,ZK	6
Terminology and d	lefinitions from the area of quality and reliability and their control, philosophy of quality, systems of quality control in the world. Reliab	ility as a part of qu	ality. Basic
definitions from the	e area of reliability, basic distributions used in reliability and their basic characteristics. Back-up using a warm and cold standby, type	s of warm and cold	l standbys.
Reliability of compo	nents and systems, calculation of reliability using composition and decomposition. and using a method of a list. Basic statistical metho	ds and tools joined	l with quality
control, mai	nagerial tools for quality control. Techniques FMEA and QFFD, house of quality. Capability of a process. Taguchi loss function. Audits	. Statistical inspect	tion.

BE2M37RNVA Radio Navigation	Z,ZK	6					
The course introduces students to the terrestrial and satellite radio navigation and radar systems. Students get knowledge of the radio navigation syst	I ' I	-					
navigation and radar signals and methods of their processing. They become familiar with coordinate systems, fundamentals of celestial mechanics, and n							
Students get knowledge of practical applications and the integration of navigation systems.							
BE2M37SSPA Statistical Signal Processing	Z,ZK	6					
The course provides fundamentals in three main domains of the statistical signal processing: 1) estimation theory, 2) detection theory, 3) optimal and ac							
signal processing is a core theory with many applications ranging from digital communications, audio and video processing, radar and radio navigation,	measurement and	experiment					
evaluation, etc.							
BE3M33ARO1 Autonomous Robotics	Z,ZK	6					
The Autonomous robotics course will explain the principles needed to develop algorithms for intelligent mobile robots such as algorithms for: (1) Mapping the principles needed to develop algorithms for intelligent mobile robots such as algorithms for: (1) Mapping the principles needed to develop algorithms for intelligent mobile robots such as algorithms for: (1) Mapping the principles needed to develop algorithms for intelligent mobile robots such as algorithms for: (1) Mapping the principles needed to develop algorithms for intelligent mobile robots such as algorithms for: (1) Mapping the principles needed to develop algorithms for intelligent mobile robots such as algorithms for: (1) Mapping the principles needed to develop algorithms for intelligent mobile robots such as algorithms for: (1) Mapping the principles needed to develop algorithms for intelligent mobile robots such as algorithms for: (1) Mapping the principles needed to develop algorithms for intelligent mobile robots such as algorithms for: (1) Mapping the principles needed to develop algorithms for intelligent mobile robots such as algorithms for: (1) Mapping the principles needed to develop algorithms for intelligent mobile robots such as algorithms for: (1) Mapping the principles needed to develop algorithms for intelligent mobile robots such as algorithms for: (1) Mapping the principles needed to develop algorithms for intelligent mobile robots such as algorithms for: (1) Mapping the principles needed to develop algorithms for intelligent mobile robots such as algorithms for: (1) Mapping the principles needed to develop algorithms for intelligent mobile robots such as algorithms for: (1) Mapping the principles needed to develop algorithms for intelligent mobile robots such as algorithms for intelligent mobile needed to develop algorithms for intelligent mobile robots such as algorithms for intelli	-						
sensors calibration (lidar or camera). (2) Planning the path in the existing map or planning the exploration in a partially unknown map and performing the p It is assumed that students of this course have a working knowledge of optimization (Gauss-Newton method, Levenberg Marguardt method, full Newton m							
(gradient, Jacobian, Hessian), linear algebra (least-squares method), probability theory (multivariate gaussian probability), statistics (maximum likeliho	,,	,					
estimate), python programming and machine learning algorithms. This course is also part of the inter-university programme prg.ai Minor. It pools the best		-					
provide students with a deeper and broader insight into the field of artificial intelligence. More information is available at https://prg.	.ai/minor.						
BE3M37KIN Space Engineering	Z,ZK	6					
The subject acquaints students with the basics of physics of the space environment and the technologies used in space systems, satellites, spacecrafts							
used for the design and preparation of space missions. Subject matter includes a detailed description of the instrumentation of satellites and spacecrafts							
influences of the space environment, and analysis of instruments and systems for spacecrafts and methods of their testing. It provides a basic overview of	-	-					
and their applications. The course also covers optoelectronics in space systems, sensors used, their modeling and description. It discusses the principl simulations and their processing.	es of underlying ca	ilculations,					
BE3M37LRS Aeronautical Radio Systems	Z,ZK	6					
The course introduces students to the aeronautical radio engineering, aeronautical analogue, digital and satellite communication systems, aeronautic		-					
satellites navigation, primary secondary and passive radiolocation. The course gets students theoretical and practical knowledge of the operation of the a	-	-					
their integration to the aircraft systems.							
BE9M04AKP Academic Writing	KZ	2					
ACADEMIC WRITING COURSE (BE9M04AKP) Objective(s): The overall aim of this course is not to increase the student's level of English, but to imp	rove the student's	skills and					
abilities of writing academically (in English). This course is not simply an opportunity for students who have registered to have someone (the instructor)	simply proofread a	and correct					
their texts - the ultimate goal of the course will be that the student is able to write (better) in English at an academic level. If a student's level of English i							
of this course (B2 Upper-Intermediate), it is the student's responsibility to take action to improve it (outside of this course). It is hoped that by working and	writing in English c	on a regular					
basis throughout this course that participants will, naturally, improve their level of English in one way or another.	1/7	0					
BE9M04PRE Presentation Skills The overall aim of this course is to develop communication and language skills in order to plan and deliver an effective presentation. Students will be taken by the statement of th		2					
key stages of giving presentations, from planning and introducing to concluding. Students are guided, using interactive methods, to communicate their t		-					
and structured order - and in as brief or succinct a way as possible. Emphasis is placed on independent, critical thinking and the correct formulation of	-	-					
this course students will practice skills that will enable them to become better speakers and presenters.		0					
BE9M35OFD Estimation, Filtering and Detection	Z,ZK	4					
This course will cover description of the uncertainty of hidden variables (parameters and state of a dynamic system) using the probability language and							
Based on bayesian problem formulation principles of rational behavior under uncertainty will be analyzed and used to develop algorithms for parameter							
Gaussian process regression), filtering (Kalman filter) and detection (likelihood ratio theory). We will demonstrate numerically robust implementation o	f the algorithms ap	plicable in					
real life problems for the areas of industrial process control, robotics and avionics.	7 71/	0					
BE9M35SRL Flight Control Systems The course is devoted to classical and modern control design techniques for autopilots and flight control systems. Particular levels are discussed, start	Z,ZK	6 ers attitudo					
angle stabilizers, to guidance and navigation systems. Next to the design itself, important aspects of aircraft modelling, both as a rigid body and consider							
are discussed	ing normality of the	o on dotaro,					
BE9M36BEP Unmanned Vehicles	Z,ZK	4					
Course is focused on area of unmanned systems. The focus will be primarily on unmanned aerial systems, but topics will cover unmanned surface and g		vell. Course					
will in details cover structural design, propulsion, sensors for navigation, stabilization and control and telemetric systems. Topics will cover modern method	ds for navigation, fli	ight control,					
including trajectory following and target tracking. Besides this students will gain knowledge about trajectory planning and areas of application from the	perspective of user	r payload.					
Legal issues related to unmanned systems operation will be discussed as well.							
BE9M38AML Aerodynamika a mechanika letu	Z,ZK	6					
The course provides overview of key findings from aircraft aerodynamics and flight mechanics. In the first part, students are familiar with models and incompressible fluid. In the second part there are derived equations describing force and rotating effects of flow on the surface of the airfoils and wings							
effects of compressibility are derived in the next part. These findings are applied on flow around the airfoils and wings at high subsonic and supersonic sp	•						
there are discussed basic modes of flight mechanics and basic design methods of air propellers.							
BE9M38EML Experimentální metody v letectví a zkoušení letade	KZ	4					
Introduction to the basic methods of measuring non-electrical quantities, procedures for conducting engineering experiments, evaluation and processing	g of data. Introducti	on to basic					
methods of aircraft specifics testing. Processing of individual labs and practical demonstrations of experimental techniques and pro	ocedures.						
BE9M38INA Integrated Modular Avionics	Z,ZK	6					
The course Integrated Modular Avionics (IMA) focuses on a modern concept of the approach to the development and design of aircraft electronics (avior							
distributed HW systems to SW blocks. They use high-speed connections to exchange data in applications related to paid air transport. The existing re		-					
sharing define the requirements for the accuracy, reliability, and functionality of electronic systems even in the event of a failure. In the course, student							
requirements for so-called safety-critical multi-sensor systems, methods of data processing from predetermined systems, fault detection methods, select control system in parallel architectures, bus technology, and methods of testing/certification of aircraft instruments.	sion of primary con	nputer and					
BE9M38LKS Aircraft Structures and Materials	Z,ZK	5					
BE9M38POL Aircraft Propulsion	Z,ZK Z,ZK	5					
This course gives basic knowledge of the aircraft propulsion theory, thermal cycles of aircraft propulsion	· · ·	-					
The influence of design parameters on propulsion system efficiency, specific fuel consumption and thrust is analyzed for the given flight velocity. Desi		-					
propulsion units are introduced and function of their components is described. The focus is given on the comparison of various systems and the cho		-					
Enviromental aspects are mentioned together with the common and alternative fuels and energy sources.							

BE9M38PRM	Project Management and Marketing	Z,ZK	2					
Currently it is in enterprises carried out much of the work in the form of one-off projects. These projects are often a crucial part of the strategic management of the business. The aim								
of the project might	of the project might be, for example, the rapid introduction of new products into production and its subsequent application in the market and helps to project management, and marketing.							
BE9M38PSL	Aircraft Avionics	Z,ZK	6					
The subject is focu	sed into a field of aircraft avionics including principles, sensors, measurement and evaluation systems and signal/data processing m	ethods. The subje	ct goes into					
details of studied	systems, i.e. engine and aircraft monitoring systems, power systems, pressure-based systems, low-frequency navigation means, and	d flight recorders. T	he subject					
introduces current	y used technology and methodology on aircraft and thus serves to understand fundamentals of avionics. Inertial navigation systems	are discussed in n	nore details					
	as well as their aiding systems and sensors. The course focuses on both small and large aircraft as well as on UAV suited avic	nics.						
BE9M38TYP	Team Project	KZ	6					
BE9M38VBM	Videometry and Contactless Measurement	Z,ZK	4					
This course focuse	o on CCD and CMOS video sensors, and optoelectronic sensors in general and their use in contactless videometric measurement sys	tems. Further optic	al radiation,					
its features, behavi	or and its use for acquiring object parameters, optical projection system, design of measurement cameras and processing of their sig	nal will be presente	ed. Students					
	will design, realize and debug an independent project ? "Optoelectronic reflective sensor", during labs.							
BEEZM	Safety in Electrical Engineering for a master's degree	Z	0					
The course prov	des for students of all programs periodic training guidelines for health and occupational safety and gives knowledge of electrical haza	ard of given branch	n of study.					
Students receive indispensable qualification according to the current Directive of the Dean.								
For undeted information and http://bilaluaiba.co.uut.co/f0.html								
For updated information see <u>http://bilakniha.cvut.cz/en/f3.html</u>								
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